# Dynamic genetic models revision for robot assisted scientific discovery

A. COUTANT, C. ROUVEIROL et al.





### Eve and the AdaLab (Adaptive Laboratory) project

- AdaLab: CHIST-ERA project for cheaper, faster & better scientific discovery.
- Objective: framework for (semi-)automated knowledge discovery in systems biology.



- Eve: Manchester's robot scientist, able to perform experiments and output results [King 2009]
- LIPN role: machine learning for model revision & experiment selection

### Diauxic shift (DS) in S. Cerevisiae

• Diauxic Shift = transition between growth phases: 1) glucose  $\rightarrow$  ethanol; 2) ethanol  $\rightarrow CO_2$ .



- Goal: improve state of the art DS model [Geistlinger 2013] using Eve
- DS inference: auto analysis of curve features, mostly the post shift growth rate
- Experiment space: 1-gene KO, nutrient levels, temperature & O2

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### Model description

- Yeast model = regulatory + metabolic model
- Regulatory model: dynamic Bayesian network (DBN) with linear Gaussian conditionals, over regulatory and metabolic genes. TO LEARN / REVISE.



Regulatization of new gene states using state of the art model rules

 Metabolic model: Stoichiometric matrix (metabolism chemical reactions X metabolites) + enzymatic relations between metabolic genes and reactions. STATIC.

### Model simulation

Simulating for *n* times = *n* repeats of: 1) DBN inference; 2) Metabolic inference with dynamic Flux Balance Analysis (DFBA); 3) Regularization of gene state for next time step using step 2 results.



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### Generative learning w/ spanning arborescences

## Few gene regulation data is available for DS. "Fat" data, with 12 time points (samples) for over 3000 involved genes.



D : original (ti, ti+1) dataset

- Ensemble approach for DBN learning
- Combination of Edmonds arborescences
- Output = top edges by frequency ranking

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### Generative learning w/ spanning arborescences



### Results

 $\bullet~$  Lower edge ratio  $\rightarrow~$  better results, but needs more models for convergence



- Good ranking on DREAM 8 Challenges:
  - in-silico (80 samples, 20 features): 3rd
  - in-vivo (32 datasets, < 20 samples, 45 features): 2nd among no prior solutions
- AdaLab: improved the fit to real curves as compared to state of the art DS model, using it as prior

### Active experiment selection w/ error blaming

From Eve growth curves, how to detect uncertainties in a model, to actively choose next experiments?

- Reverse" simulation of Eve curves
  - DFBA with fixed growth + reaction constraint propagation to retrieve metabolic genes



 Results: good reconstruction for many strains despite partial reverse inference

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### Active experiment selection w/ error blaming

#### Gene ranking and experiment selection

- Compare regular vs. reverse simulation deviations for available Eve curves
- Rank genes according to their mean deviations across curves
- Select genes with most errors as KO experiments to perform next

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### Model revision from Eve experiments

How to perform regulatory model updates w/ Eve's phenotypic growth curves & no transcriptomic data?

### Algorithm

- KO prediction error driven
- Genes w/ high abs error are revised first
- Prior score on revisions before simulation ⇒ Restricted set of costly simulations



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### Model revision (ctd)



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### Results

- High reduction of strains prediction error (from 30% to 75%, depending on variant)
- Initializing w/ extended state of the art DS model, using spanning arborescences generative learning, gave better results than state of the art DS model alone
- Active selection of genes for revision gives better model improvement than random selection, validating active learning possibilities in AdaLab.



### An altenative view for gene selection : Identification of DS genes w/ graph abstraction

- From co-regulation net labelled with activity profile (AP) in KB.
- Enum of (closed abstract pattern, graph extension)=(c, ext) (RG groups w/ ≈ AP).
- Selection of
   [(c, ext, )), (c, ext, )] linked
   in co-regulation net.



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### Identification of DS genes w/ graph abstraction



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### On-going/Future work

- First proof of concept, "pragmatic" approach
- Enforce empirical evaluation/formalisation

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### References & Acknowledgements

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### **References & Acknowledgements**

This work was funded by CHIST-ERA's 2013 call, and supported by other AdaLab participants: University of Manchester - Ross King, Katherine Roper & Martin Carpenter; Brunel University - Larissa Soldatova & Jacek Grzebyt; KU Leuven - Jan Ramon & Alex Sarafianos; Université d'Évry Val-d'Essonne - Mohammed Elati & Daniel Trejo; Technical advisors - Patrick Courtney (SiLA) & Steve Oliver (University of Cambridge)

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