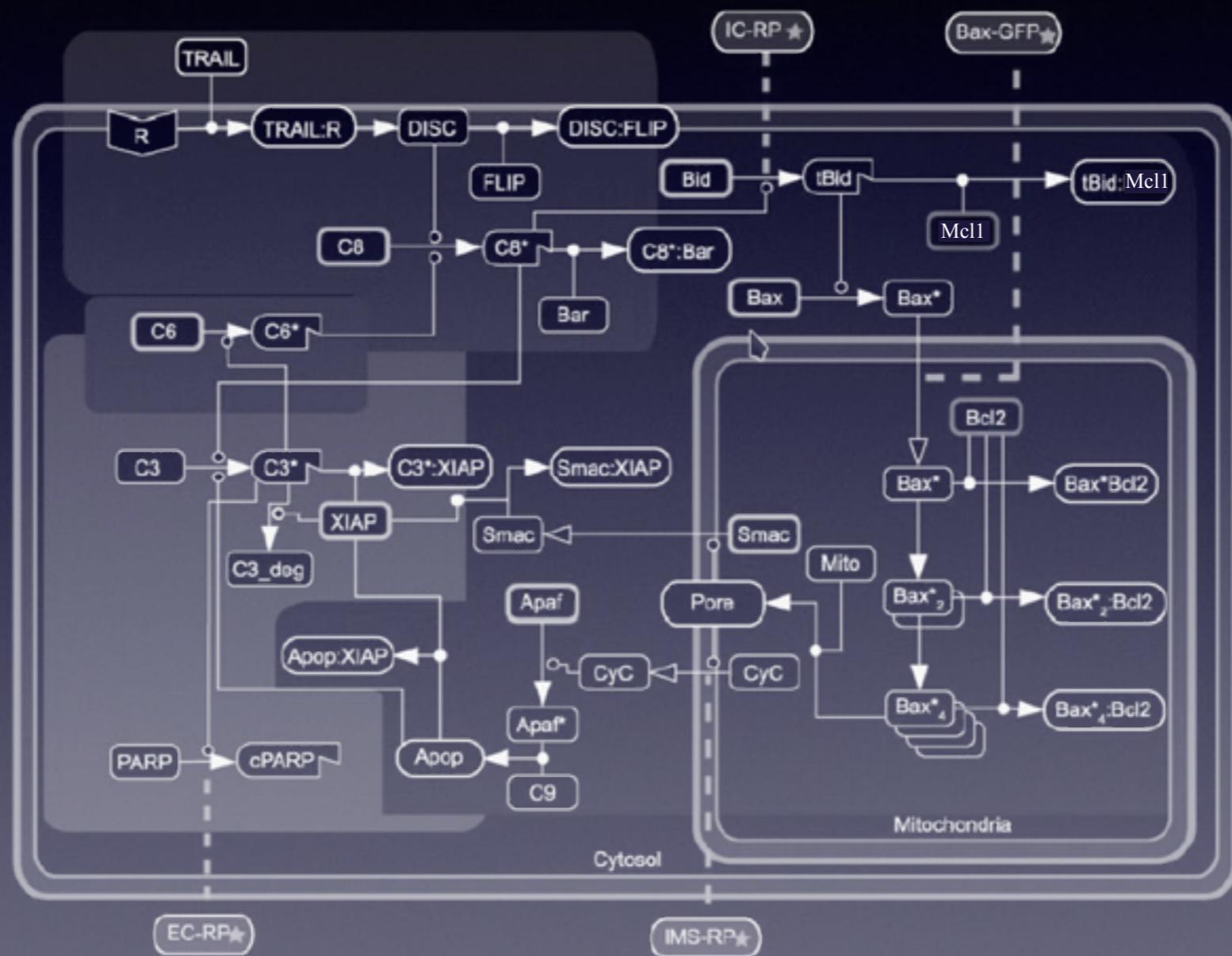


# Inference in DBNs with non-disjoint clusters

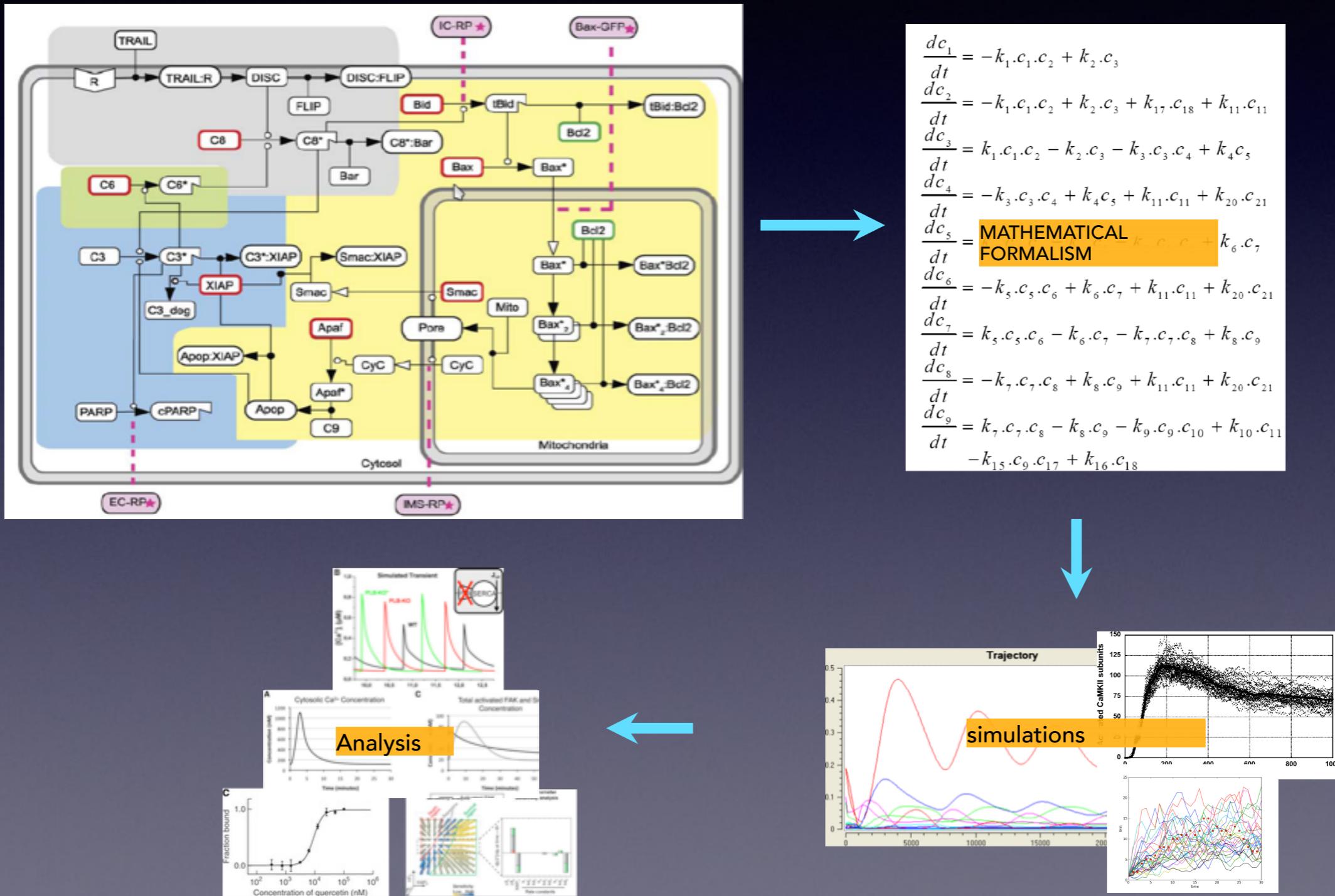
Matthieu Pichené

# Introduction

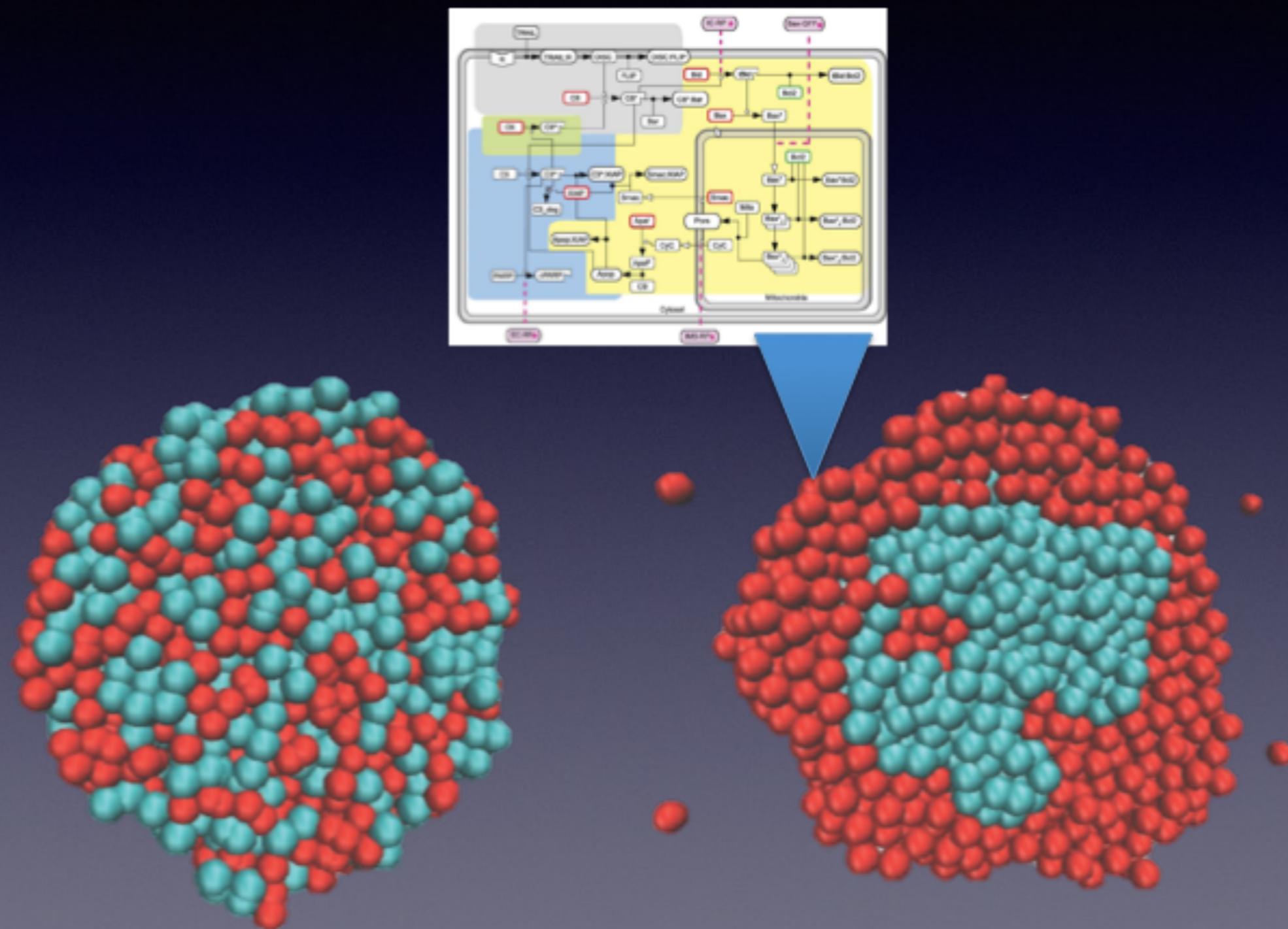
# Apoptosis pathway



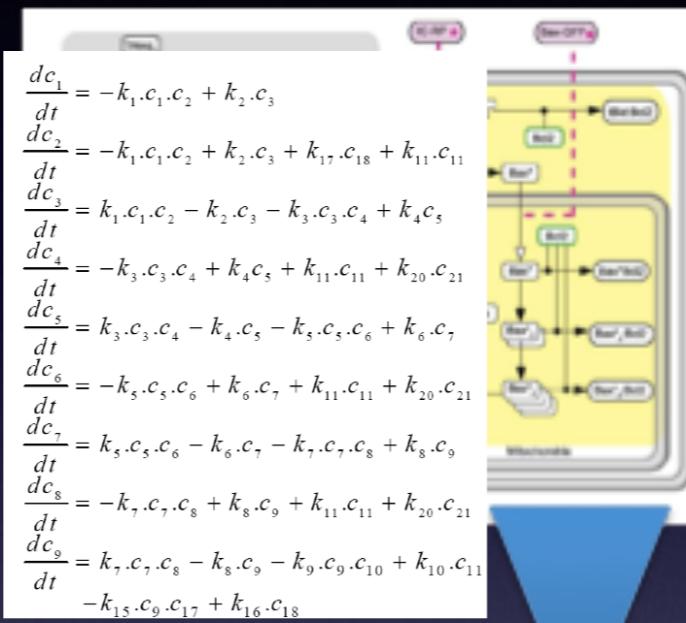
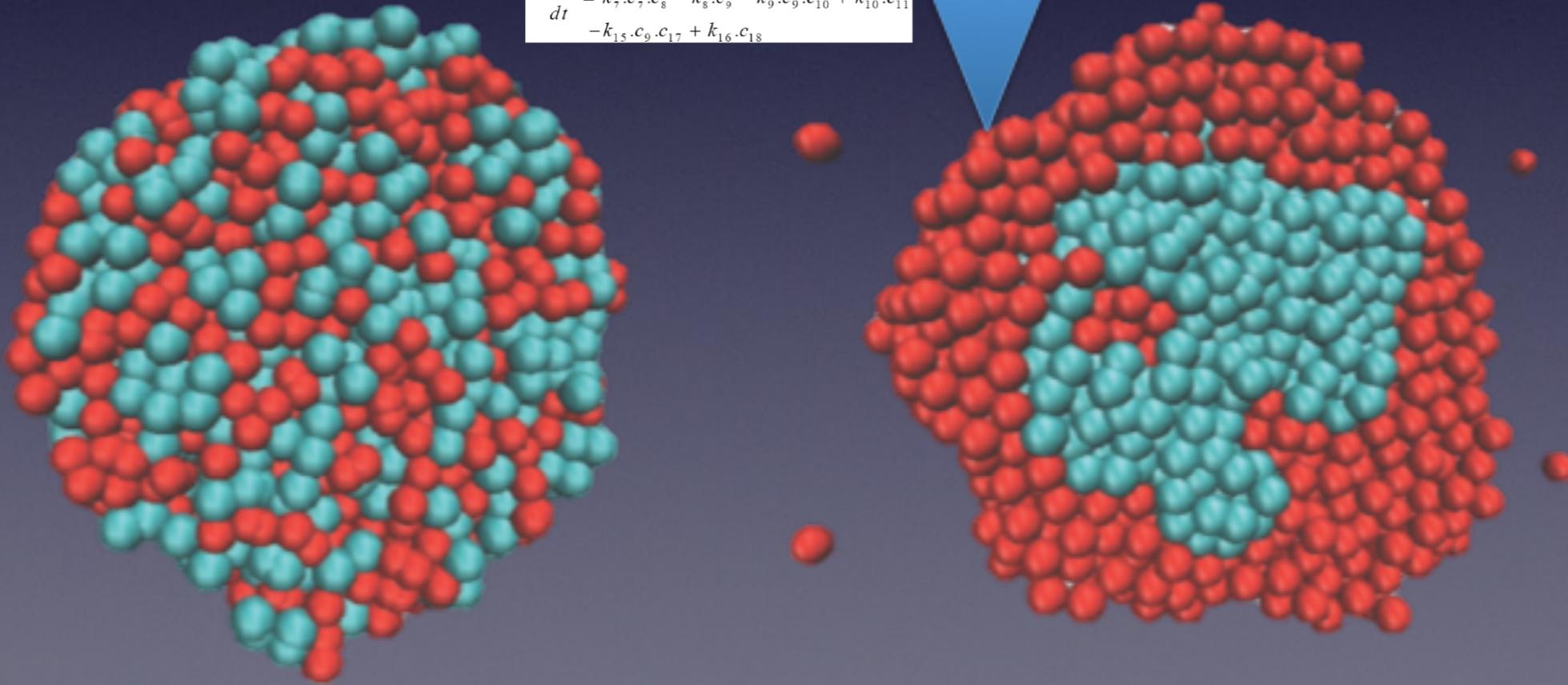
# Method



# Method

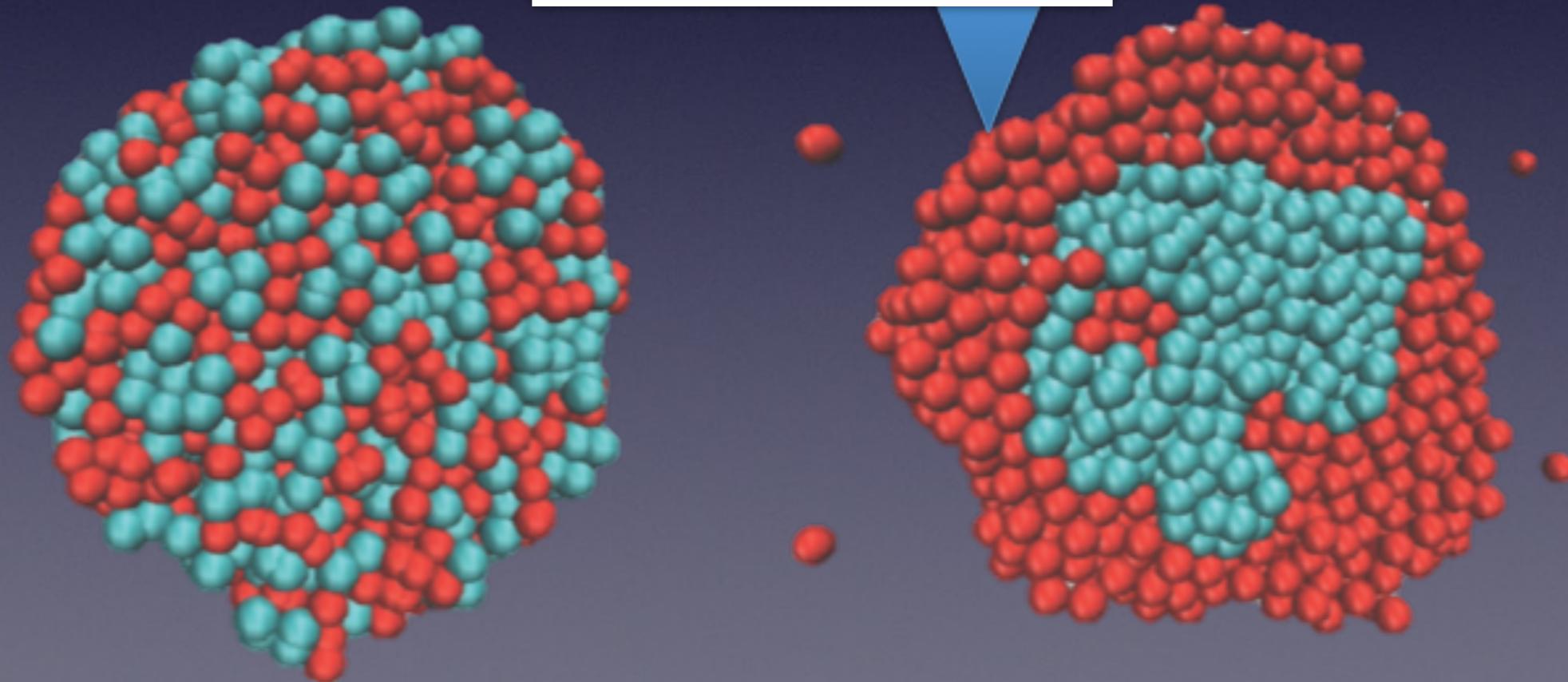


# Method



# Method

(Approximate)  
abstraction  
of the low level  
biochemical model



# DBNs

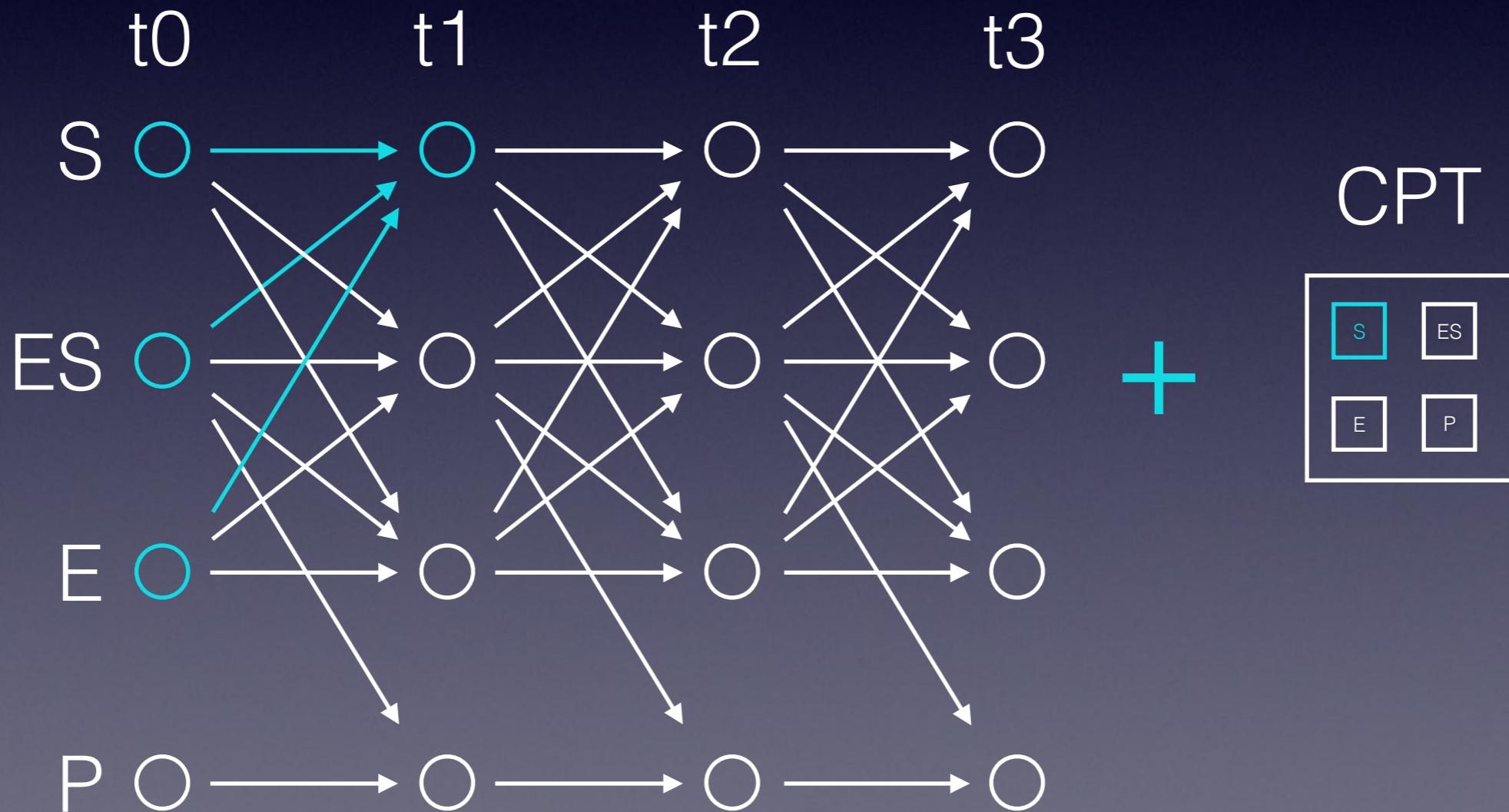


	t0	t1	t2	t3
S	O{ 1 2 3 4 5}	O	O	O
ES	O{ 1 2 3 4 5}	O	O	O
E	O{ 1 2 3 4 5}	O	O	O
P	O{ 1 2 3 4 5}	O	O	O

Every species at time point t is a random variable over a discrete number of values.

Number of configurations at each time point: Values<sup>Species</sup>

# DBNs



# CPT

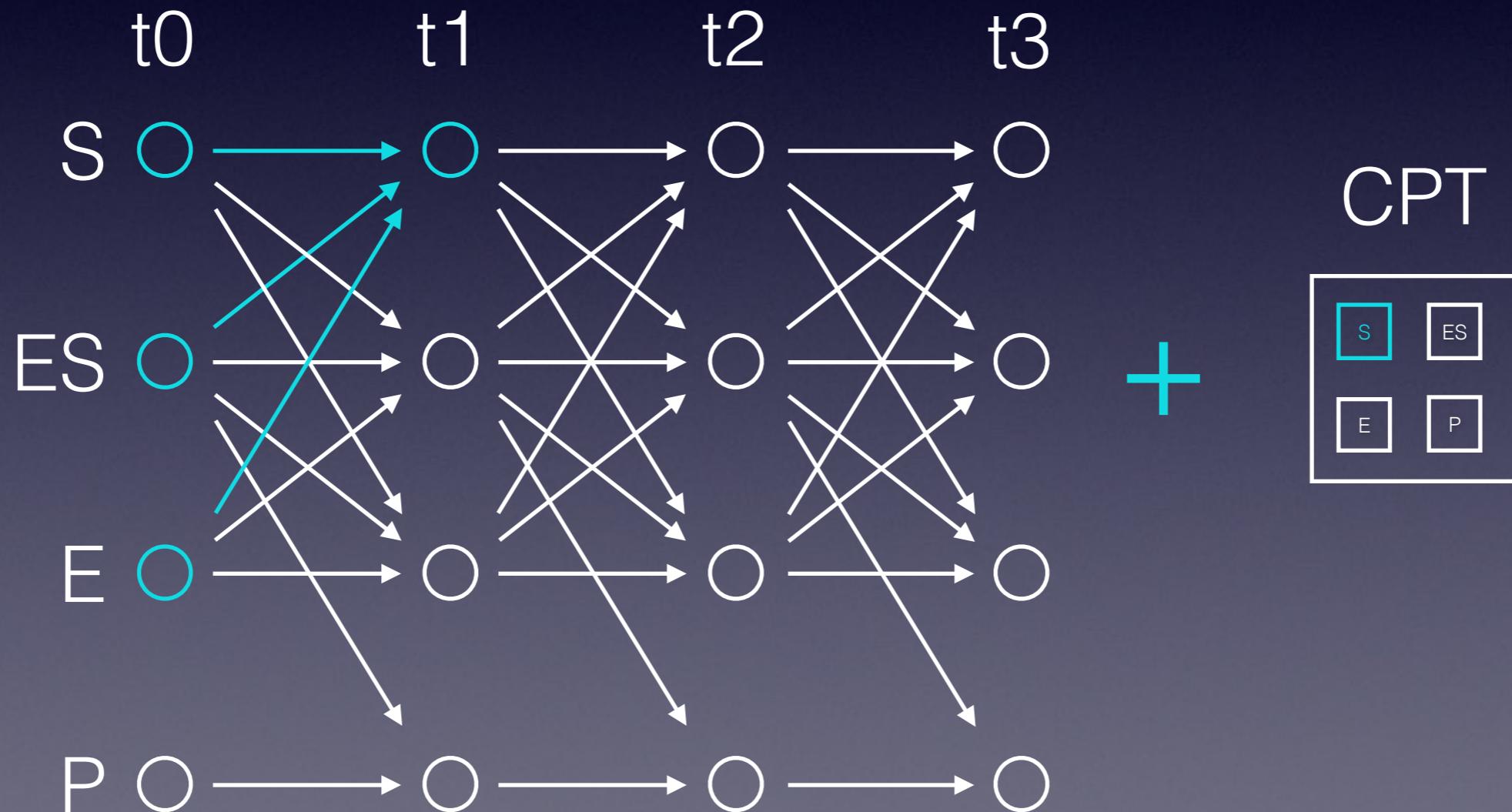


S					ES					
S	S	E	ES	Pr	ES	S	E	ES	P	Pr
1	1	1	1	0.1	1					
1	2	1	2	0.2	1					
2	2	3	3	0.1	2					
...					...					

E					P			
E	S	E	ES	Pr	P	ES	P	Pr
1					1			
1					1			
2					2			
...					...			

# DBNs

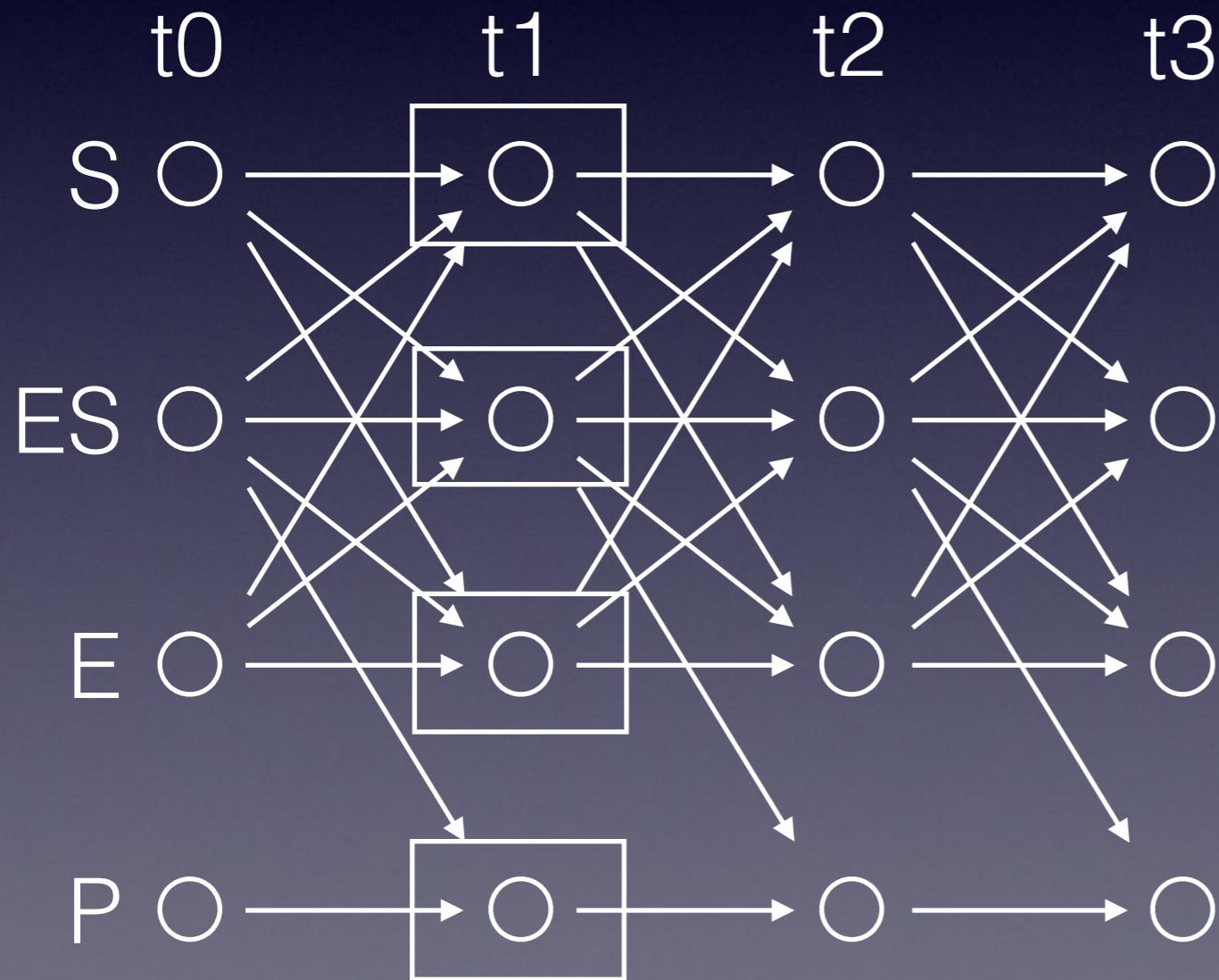


Complexity of exact inference: at least  $\text{Values}^{\text{Species}}$

# DBNs

- We need an approximation. Express configurations as product of probabilities
- Simplest idea : Consider all species independent ( Factored Frontier )

# Factored Frontier



Hypothesis : Independent

$$P^{t2}(P=h) = f(P^{t1}(P), P^{t1}(ES), CPT)$$

complexity of FF inference:  
Species x Values<sup>NbPar+1</sup>

Low accuracy

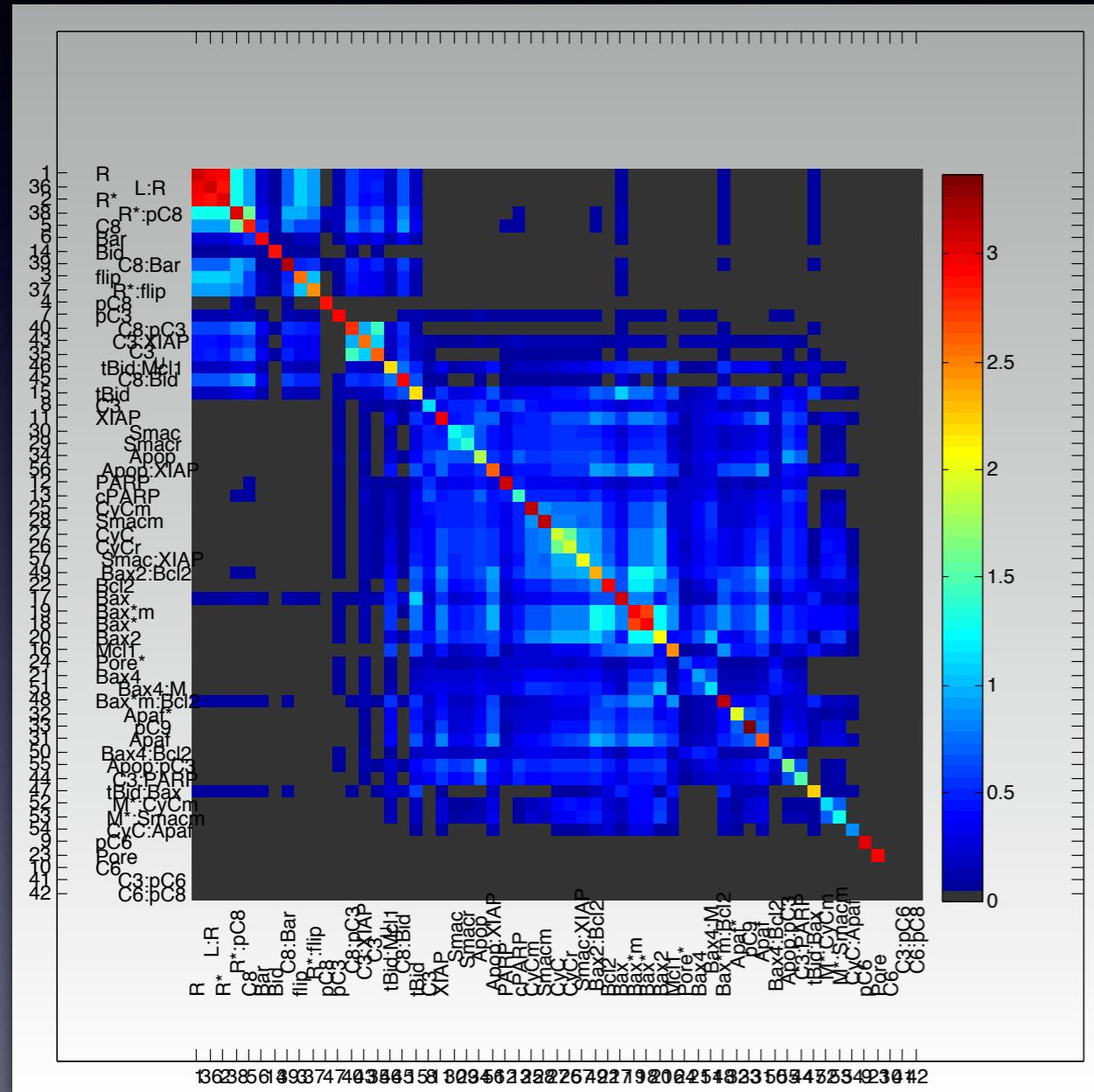
# Clustered Factored Frontier

- Use of clusters containing the species that have the most mutual information
- Clusters may vary over time
- All sets of states for species in a clusters are calculated (that limits the length of clusters)

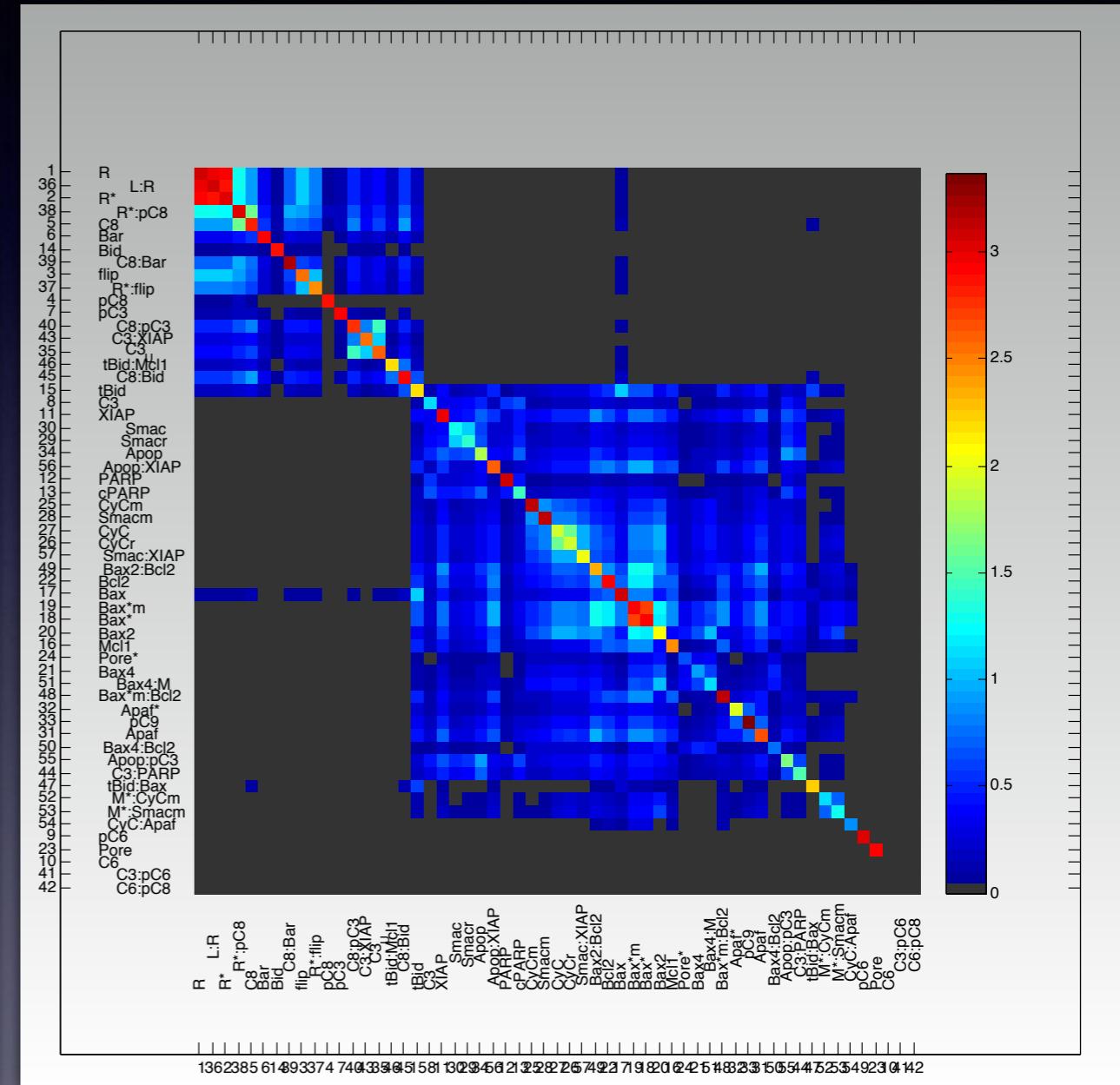
# Clustered Factored Frontier

- Use information theory (Eric) to obtain the important relations
- We (Eric) chose the tree to minimize distance  $(P(X_1 = v_1, \dots, X_n = v_n); \prod_{\ell=1}^k \frac{P((X_i)_{i \in C_\ell} = (v_i)_{i \in C_\ell})}{P((X_i)_{i \in C_\ell \cap \bigcup_{i=1}^{\ell-1} C_i} = (v_i)_{i \in C_\ell \cap \bigcup_{i=1}^{\ell-1} C_i})})$
- Tree implies cluster of size 2

# Species correlations (Eric)



Mutual information  
on the whole graph



Mutual Information  
on the Tree Approximation

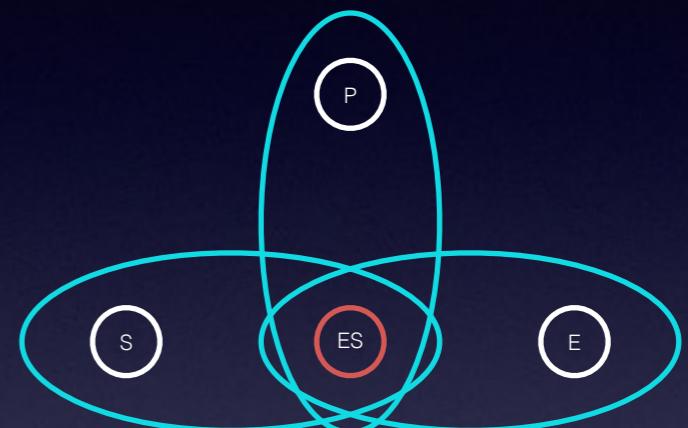
# Clustered Factored Frontier

we assume that relations not in tree are irrelevant

Hypothesis :

$$\Pr(S^t=h, ES^t=l, E^t=m, Pt=h) =$$

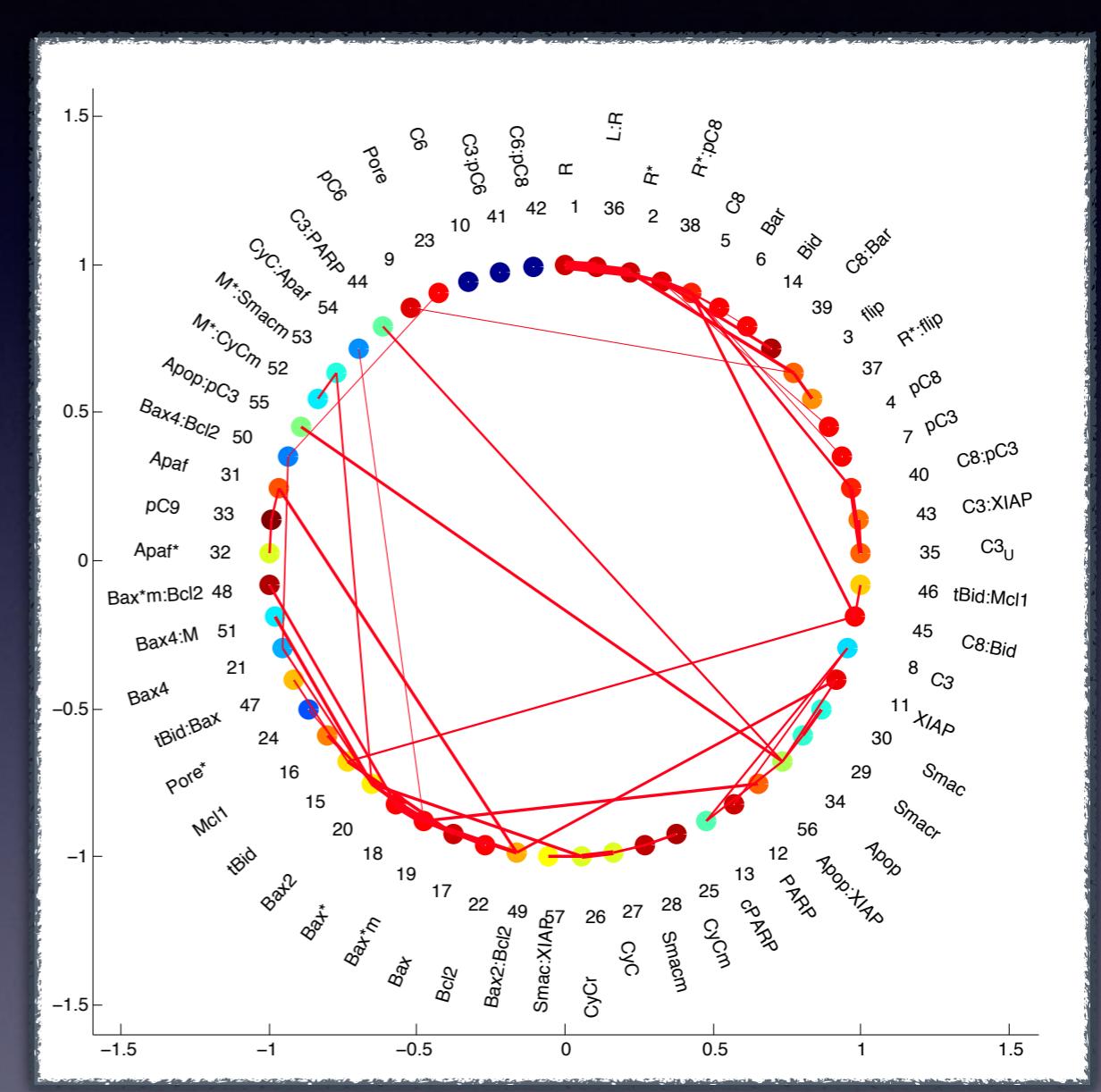
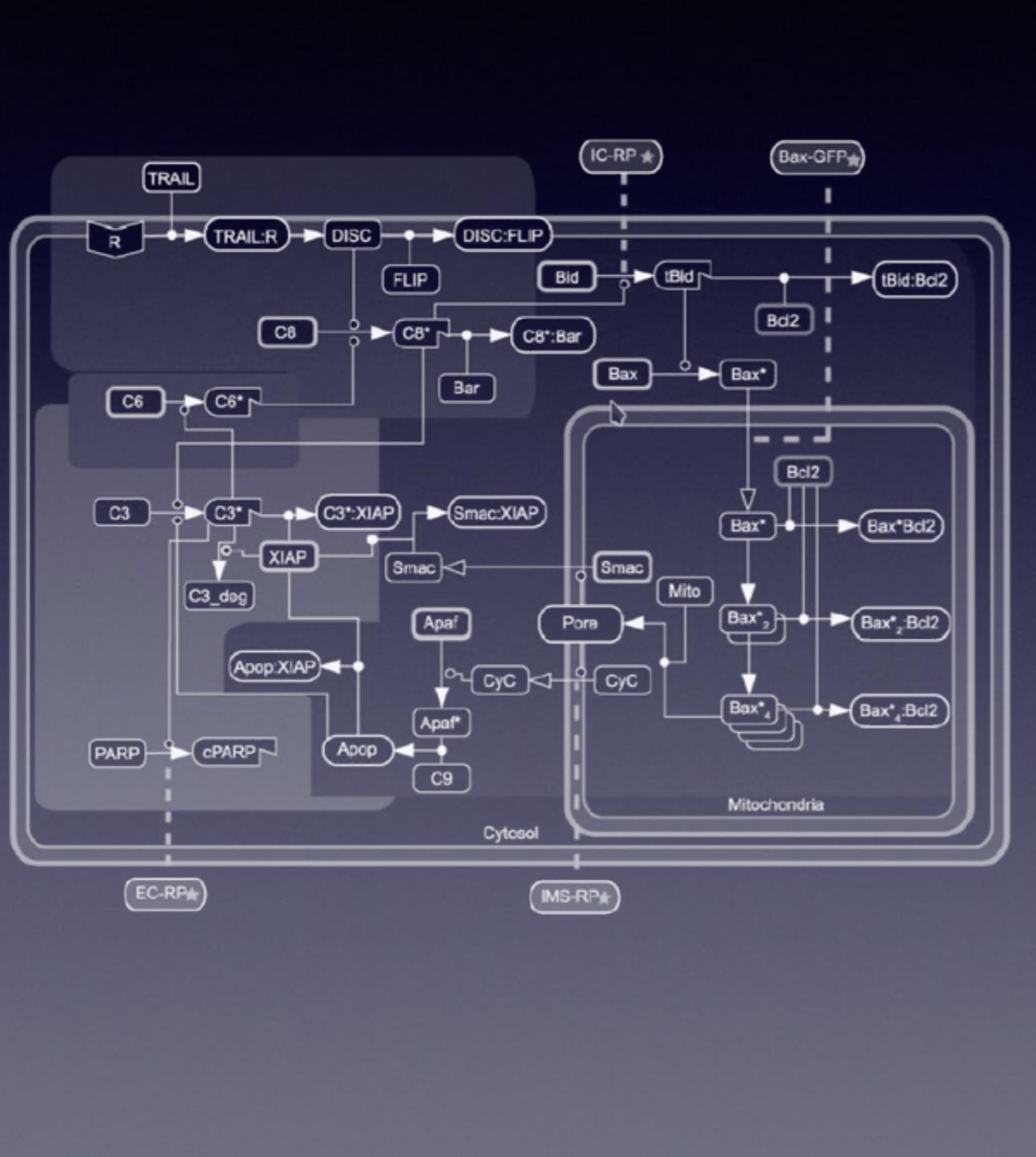
$$\Pr(S^t=h, ES^t=l) \Pr(ES^t=l, E^t=m) \Pr(ES^t=l, Pt=h)$$



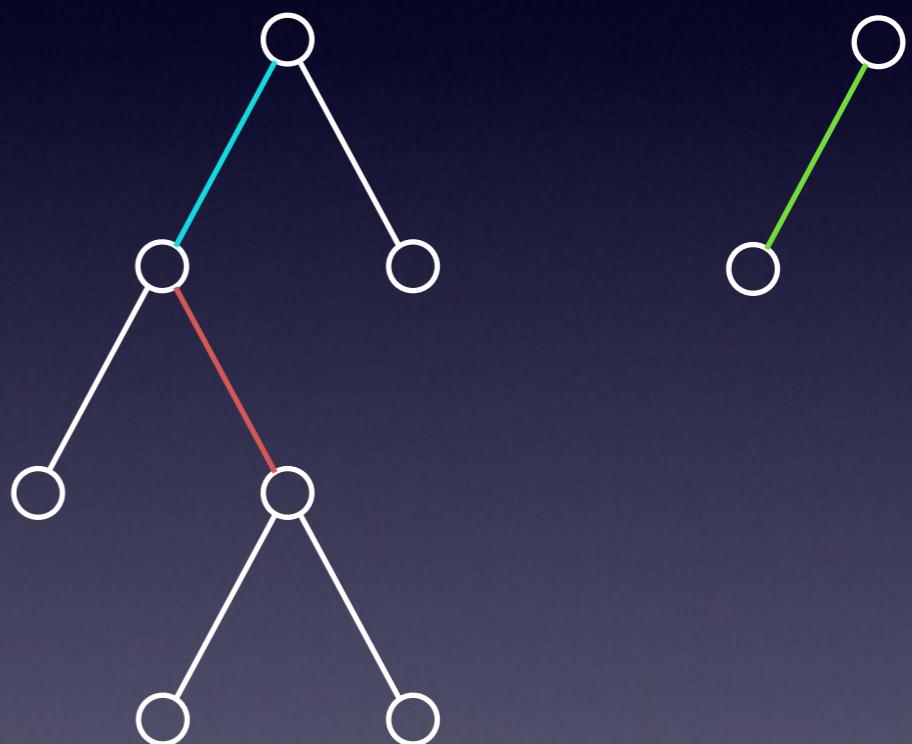
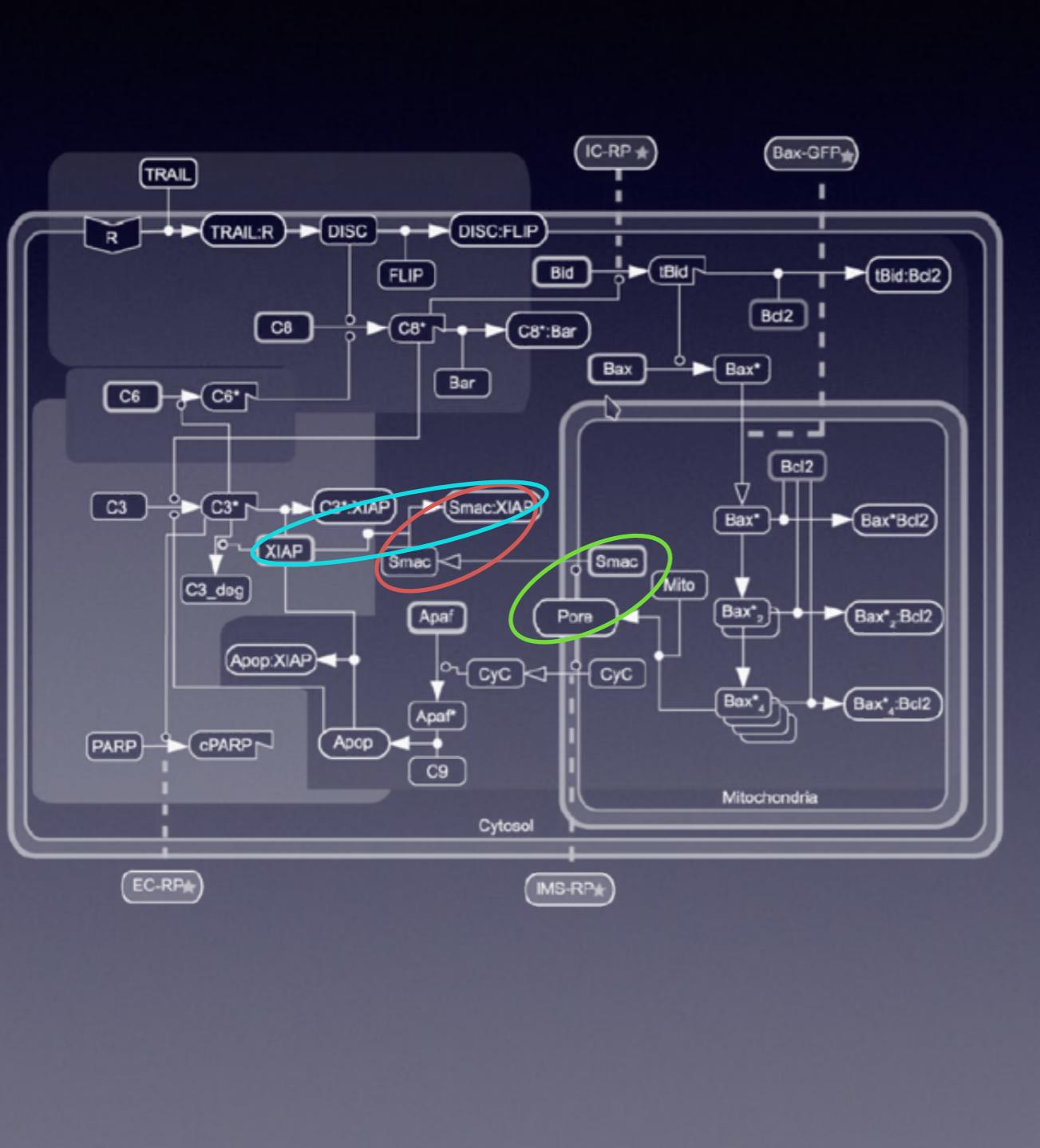
---

$$\Pr^2(ES^t=l)$$

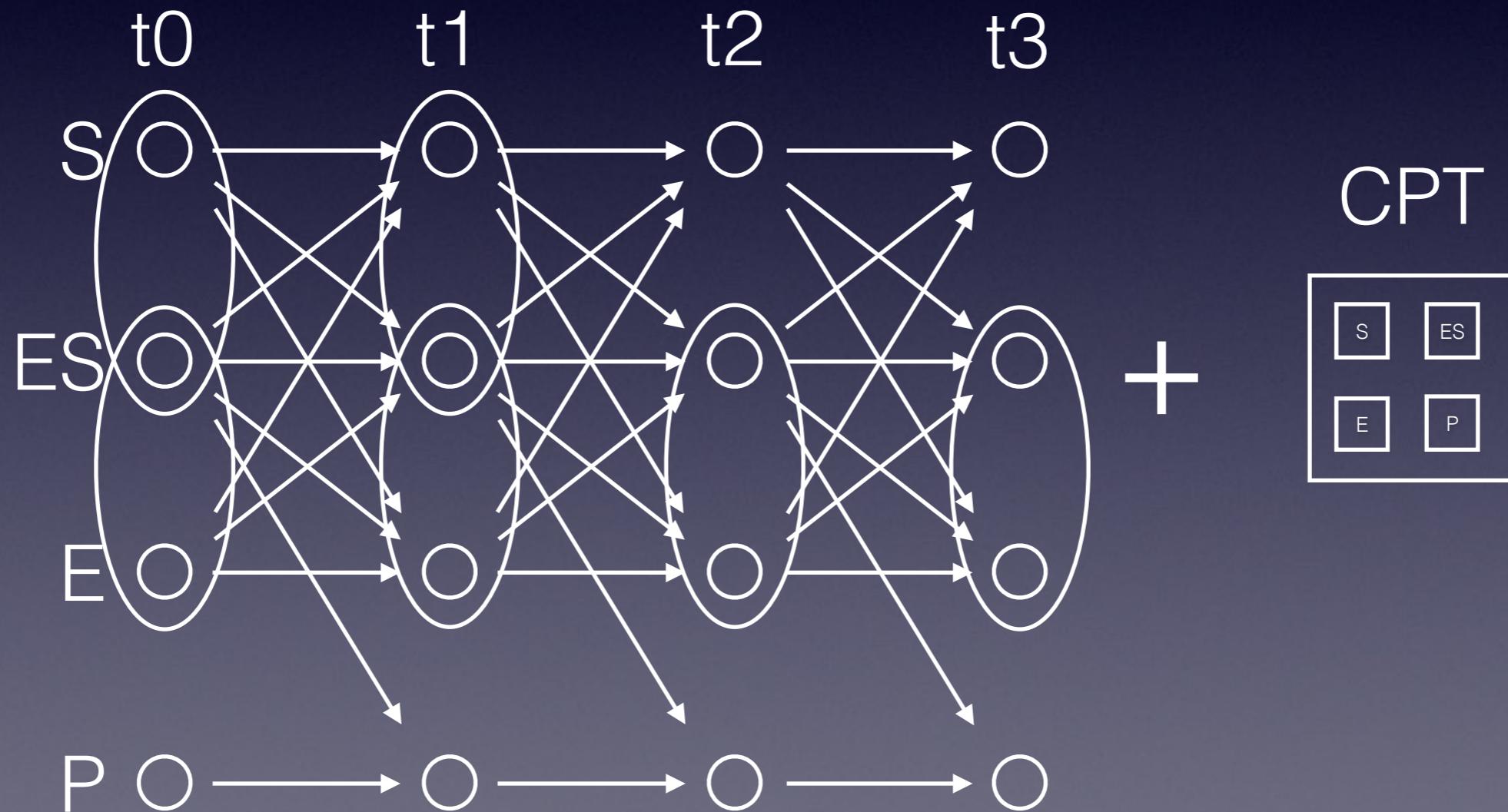
# Apoptosis pathway



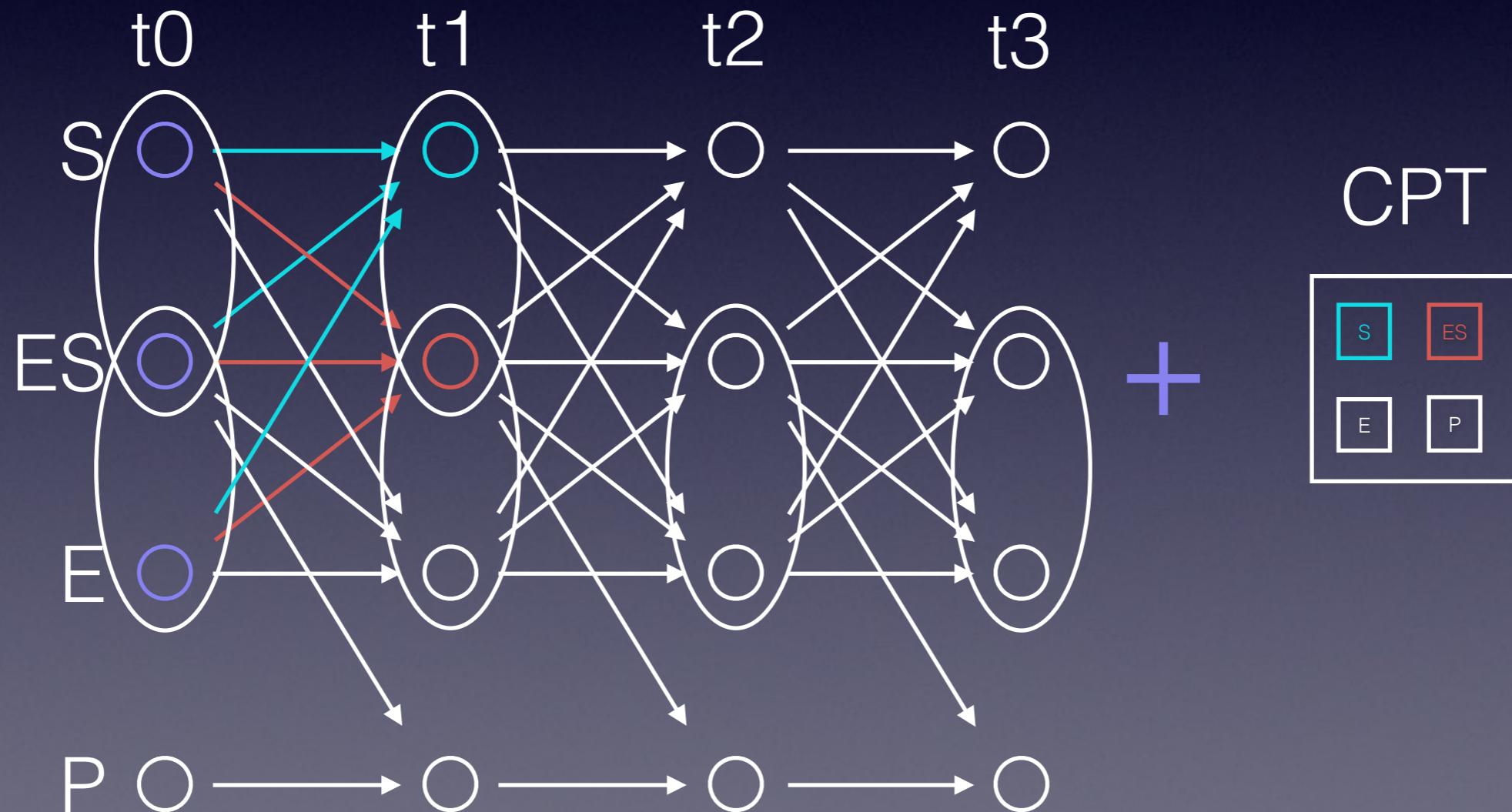
# Apoptosis pathway



# Clustered Factored Frontier



# Clustered Factored Frontier



$$P^{t1}(s', es') = \sum_{s, es, e} (P^{t0}(s, es, e) CPT(s, es, e, s') CPT(s, es, e, es'))$$

# How our algorithm work

Hypothesis :

$$\Pr(S^t=h, ES^t=l, E^t=m, Pt=h) =$$

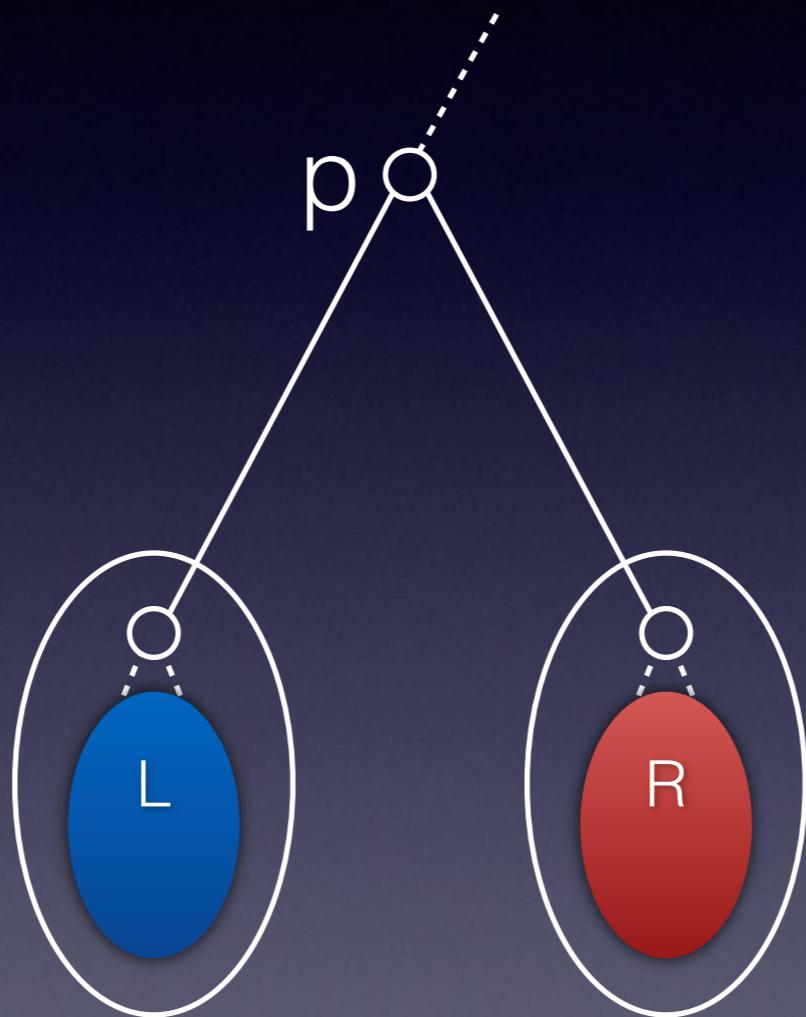
$$\Pr(S^t=h, ES^t=l) \Pr(ES^t=l, E^t=m) \Pr(ES^t=l, Pt=h)$$



---

$$\Pr^2(ES^t=l)$$

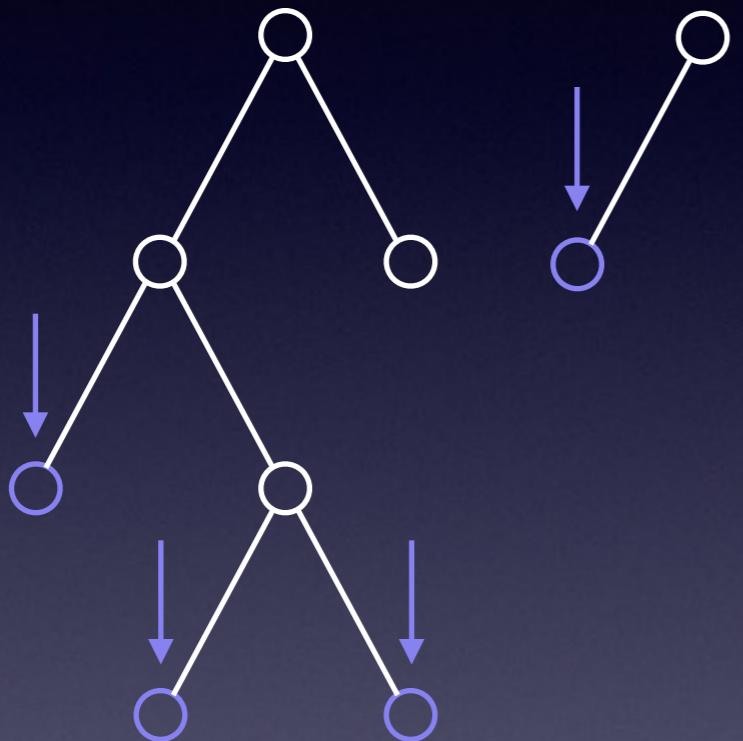
# How to compute $P(\text{parents(Cluster)})$



Proposition :

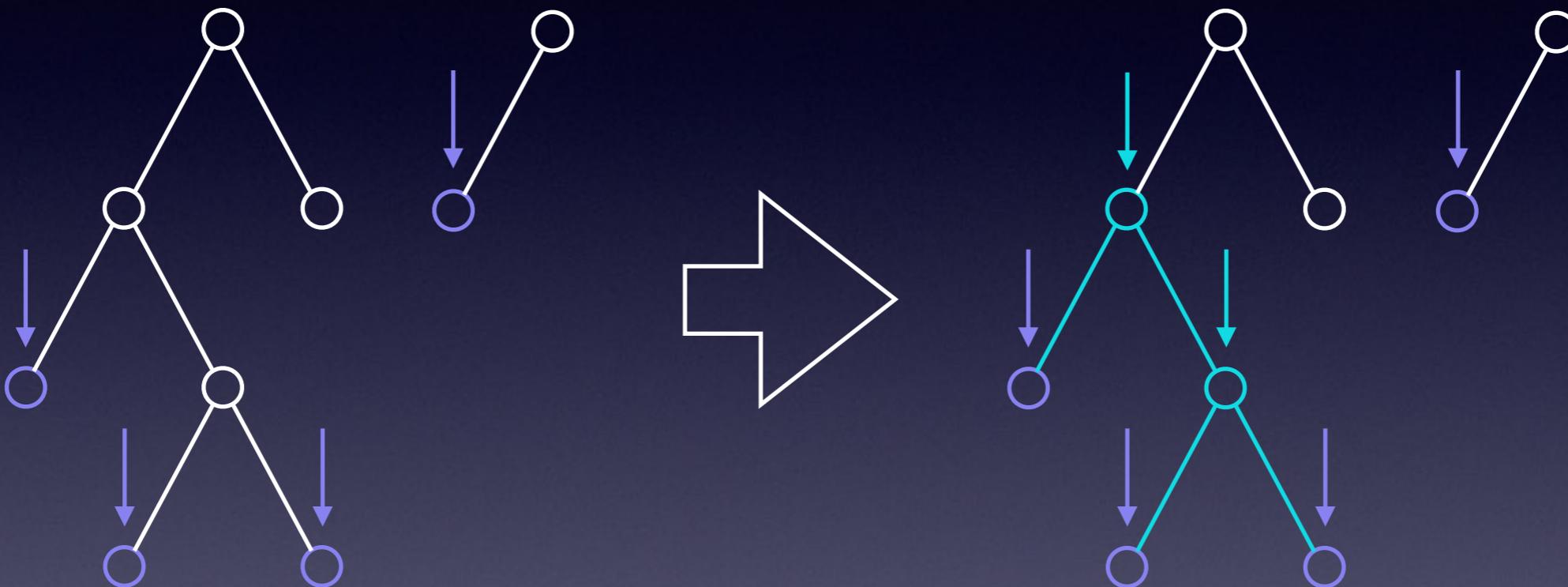
$$P(X_p = v_p, X_L = V_L, X_R = V_R) = \frac{P(X_p = v_p, X_L = V_L) \times P(X_p = v_p, X_R = V_R)}{P(X_p = v_p)}$$

# How to compute $P(\text{parents(Cluster)})$

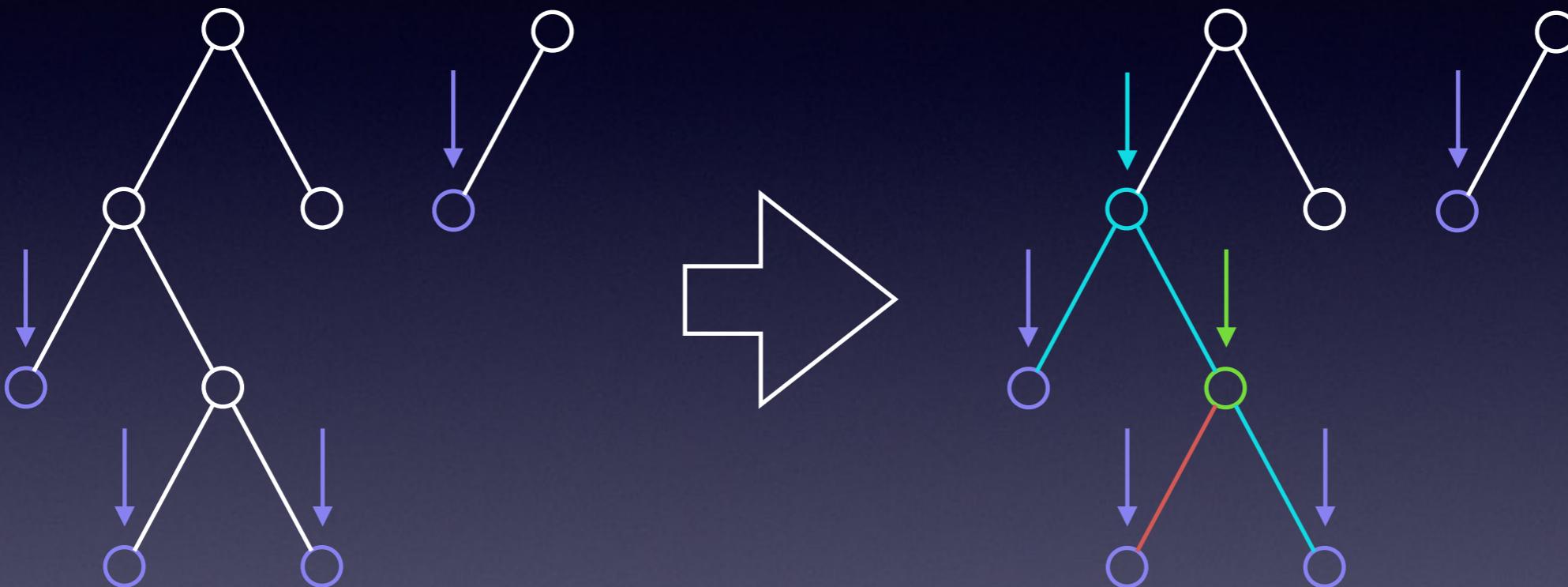


Parent\_Cluster= set of nodes necessary to use the CPTs.

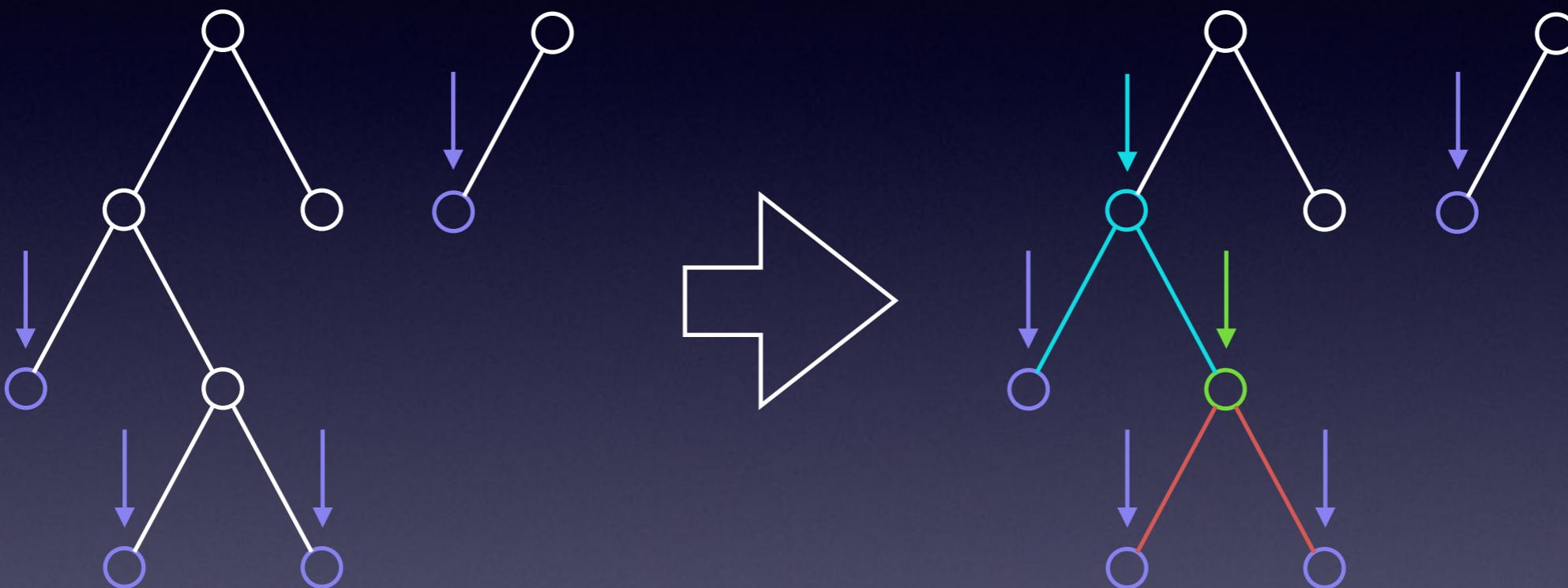
# How to compute $P(\text{parents(Cluster)})$



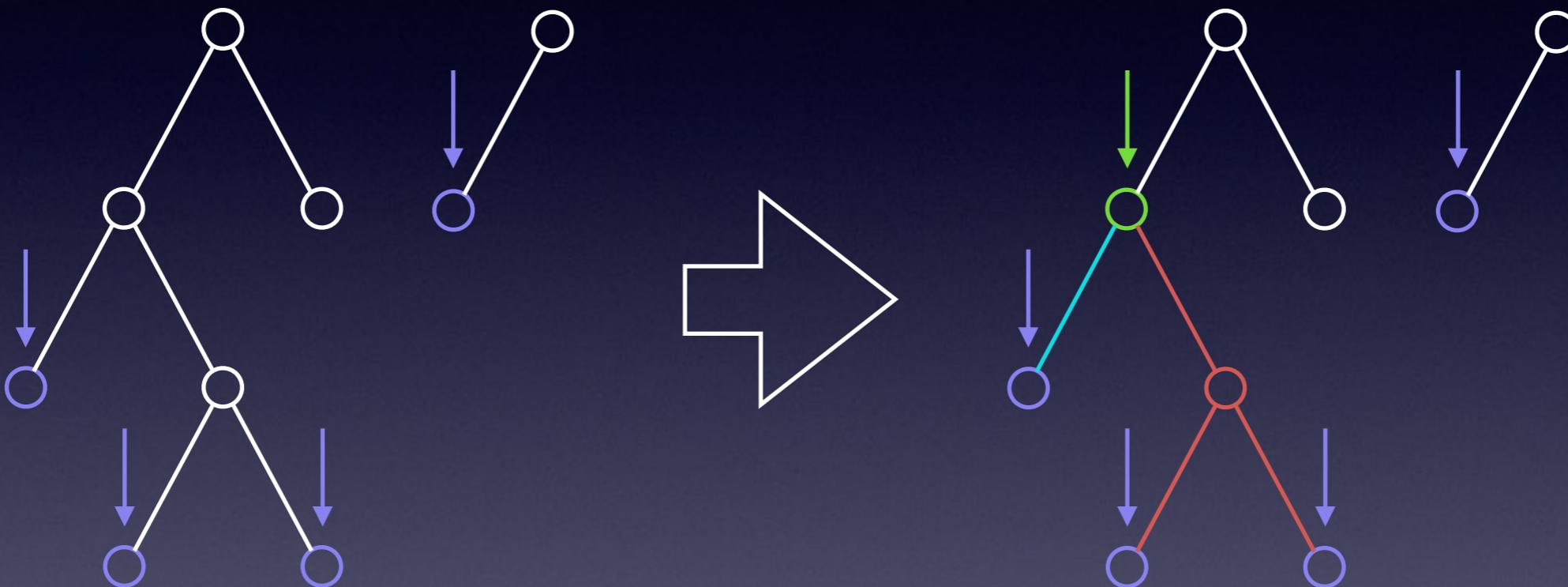
# How to compute $P(\text{parents(Cluster)})$



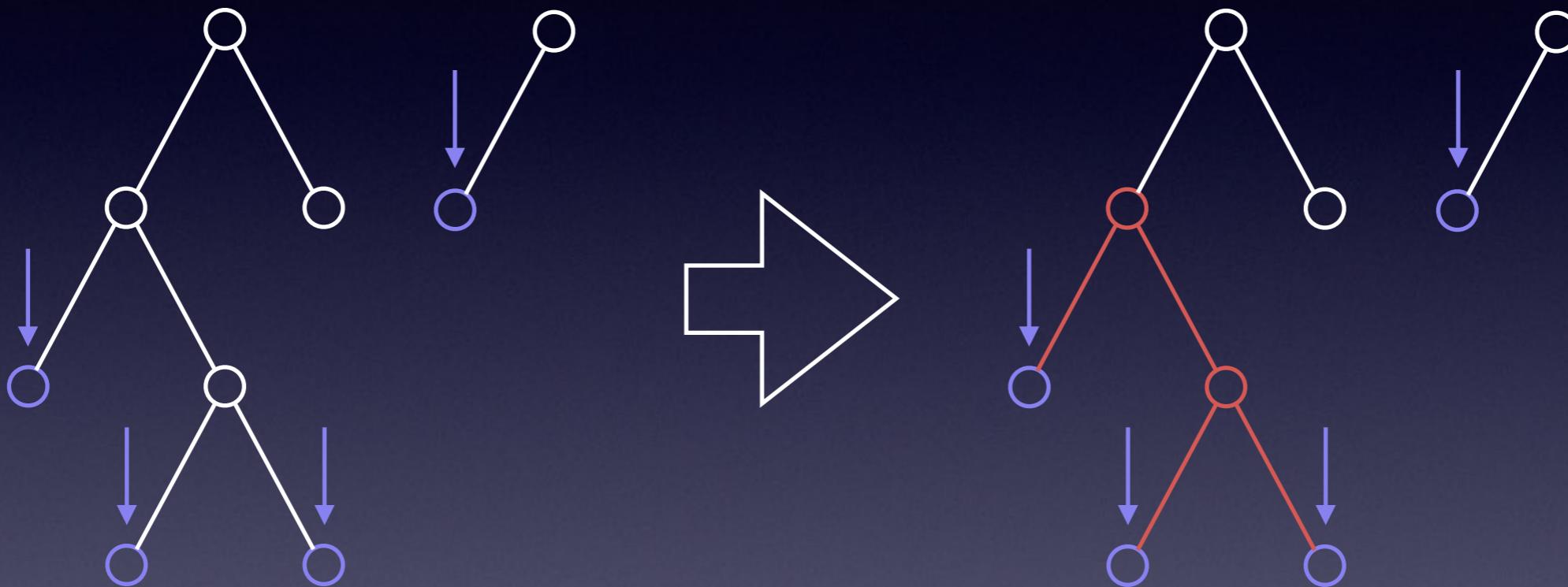
# How to compute $P(\text{parents(Cluster)})$



# How to compute $P(\text{parents(Cluster)})$



# How to compute $P(\text{parents(Cluster)})$



Independence between trees  
Complexity : Species x Values Parents\_Cluster+1

# Algorithm comparison

	FF	ClusteredFF	Exact computation
Complexity	Species x Values <sup>NbParents</sup>	Species x Values <sup>Parents_Cluster+1</sup>	> Values <sup>Species</sup>
Accuracy	Low	? but better than FF	Exact

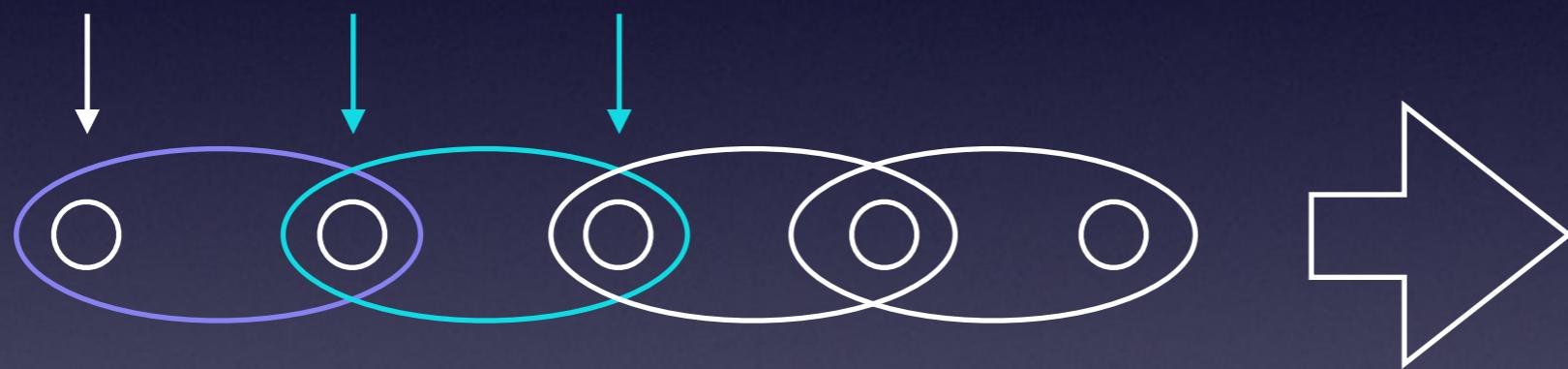
# Conclusion

- Our program is currently still being written. Results will tell if the accuracy is good or not.
- After the first results are obtained we will upgrade it to accept bigger clusters and non-tree graphs

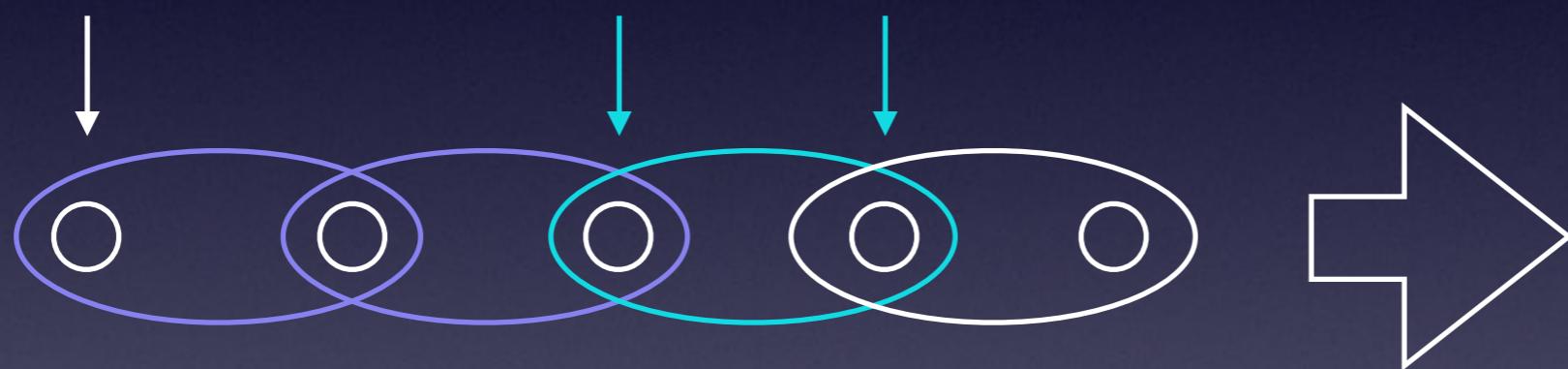
# How our algorithm work



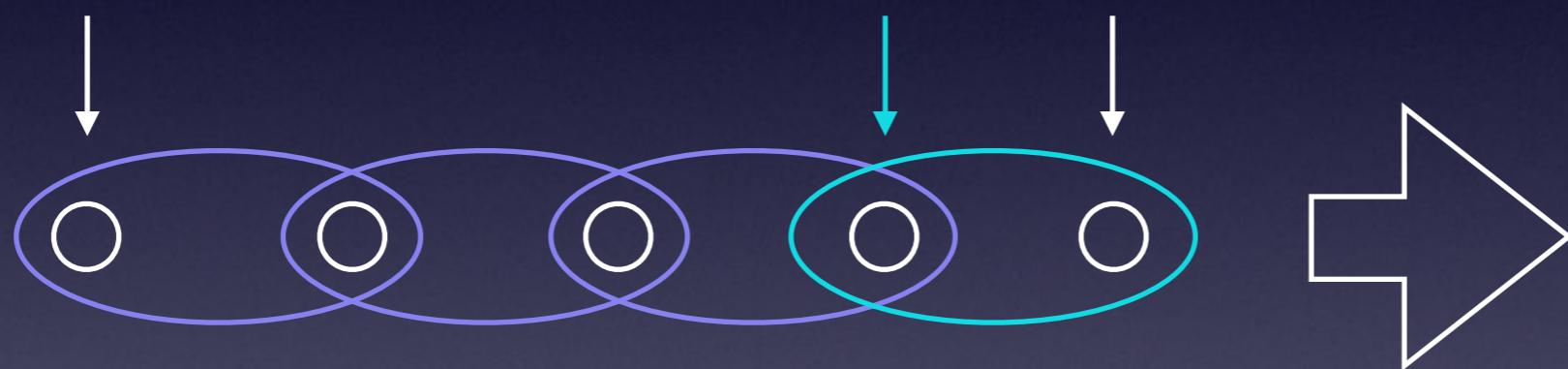
# How our algorithm work



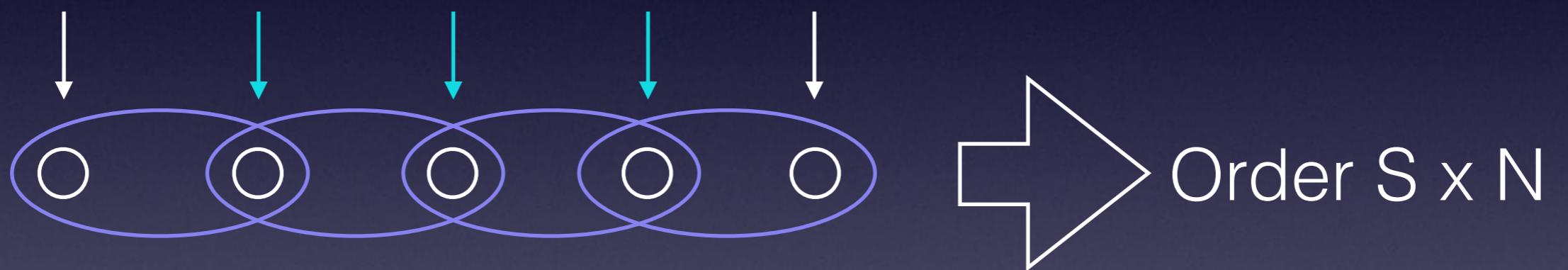
# How our algorithm work



# How our algorithm work



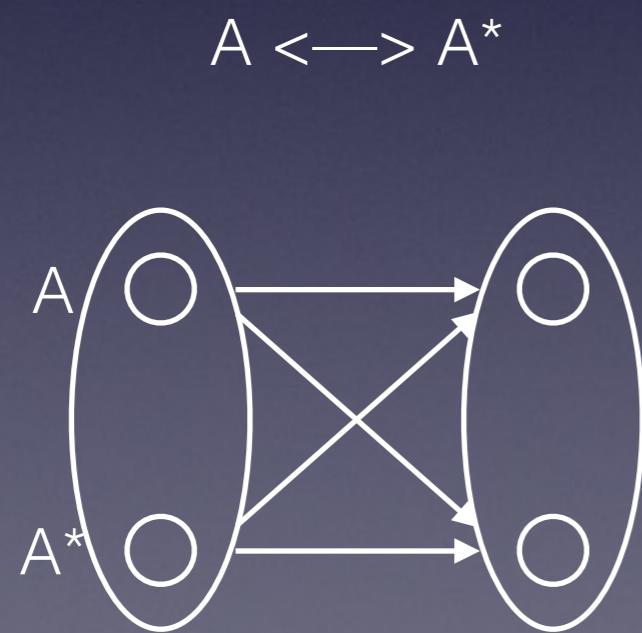
# How our algorithm work



# How our algorithm work

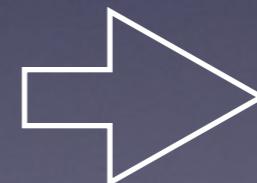
- For each time  $T$  groups of clusters are found
- Most efficient path is found to calculate each cluster
- Calculate probability using CPTs
- Results are saved, cluster probabilities are kept in memory

# Clustered Factored Frontier



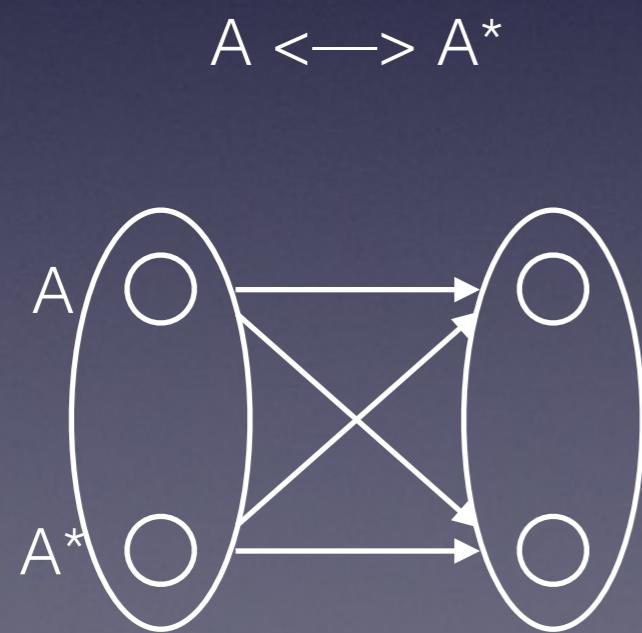
CPT:

- 98% :  $A = h \ A^* = I \rightarrow A = h$
- 2% :  $A = h \ A^* = I \rightarrow A = I$
- 2% :  $A = I \ A^* = h \rightarrow A = h$
- 98% :  $A = I \ A^* = h \rightarrow A = I$
- 2% :  $A = h \ A^* = I \rightarrow A^* = h$
- 98% :  $A = h \ A^* = I \rightarrow A^* = I$
- 98% :  $A = I \ A^* = h \rightarrow A^* = h$
- 2% :  $A = I \ A^* = h \rightarrow A^* = I$



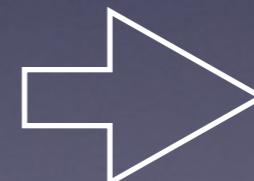
- 50%  $A = h \ A^* = I$
- 50%  $A = I \ A^* = h$
- 96.04%  $A = h, A^* = I$
- 0.04%  $A = I, A^* = h$
- 1.96%  $A = h, A^* = h$
- 1.96%  $A = I, A^* = I$
- 0.04%  $A = h, A^* = I$
- 96.04%  $A = I, A^* = h$
- 1.96%  $A = h, A^* = h$
- 1.96%  $A = I, A^* = I$

# Clustered Factored Frontier



CPT:

- 98% :  $A = h \ A^* = I \rightarrow A = h$
- 2% :  $A = h \ A^* = I \rightarrow A = I$
- 2% :  $A = I \ A^* = h \rightarrow A = h$
- 98% :  $A = I \ A^* = h \rightarrow A = I$
- 2% :  $A = h \ A^* = I \rightarrow A^* = h$
- 98% :  $A = h \ A^* = I \rightarrow A^* = I$
- 98% :  $A = I \ A^* = h \rightarrow A^* = h$
- 2% :  $A = I \ A^* = h \rightarrow A^* = I$



50%  $A = h \ A^* = I$   
50%  $A = I \ A^* = h$  :

53.04%  $A = h, A^* = I$   
53.04%  $A = I, A^* = h$   
1.96%  $A = h, A^* = h$   
1.96%  $A = I, A^* = I$