# Analogue models of computation: computing with real numbers

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Practices around Computation

# We need to talk about a discrete model

## An example of non-analogue model



The model:



















| (we assume the tape is non-empty) |                                     |                                     |                                    |                      |
|-----------------------------------|-------------------------------------|-------------------------------------|------------------------------------|----------------------|
|                                   | \$                                  | 0                                   | 1                                  | В                    |
| <i>q</i> <sub>init</sub>          | $q_{\textit{init}}, \$,  ightarrow$ | $q_{\textit{init}}, 0, \rightarrow$ | $q_{\textit{init}}, 1,  ightarrow$ | $q_1, B, \leftarrow$ |
| $q_1$                             |                                     | accept, 1                           | $q_2, 0, \leftarrow$               |                      |
| <i>q</i> <sub>2</sub>             | $q_3, \$,  ightarrow$               | accept, 1                           | $q_2, 1, \leftarrow$               |                      |
| <i>q</i> <sub>3</sub>             |                                     | $q_4^0, 1,  ightarrow$              |                                    |                      |
| $q_{4}^{0}$                       |                                     | $q_4^0, 0,  ightarrow$              |                                    | accept, 0            |

• Time = number of steps

- Time = number of steps
- Space = number of needed cells

<u>Time</u>: 6 steps  $\rightarrow O(n)$ , *n* the size of the input

Space : 2 cells  $\rightarrow O(n)$ , *n* the size of the input

Both are linear (in the size of the input), so *polynomial* in time and space.

 $\bullet\,$  Time of a TM  $\sim$  Time on the laptop...

 $\rightarrow$  Notions of time and space does not depend on the model

Church-Turing thesis: All discrete sufficiently powerful and reasonable models of computation have the same computational power as a Turing machine.



#### Putting boxes into boxes (but they are very nice boxes)



What an analogue world

Historicaly, they are the first computational machines and certainely the most accurate

 $\rightarrow$  Nothing is lost in translation

## Well, actually... An example of analogue model



## We live in an analogue world



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## We live in an analogue world: planimeter







## We live in an analogue world:







 <u>Making</u>: convert the sound into a print on a support in a spiraling groove;



- <u>Making</u>: convert the sound into a print on a support in a spiraling groove;
- Playing:
  - A head is placed on the groove;



- <u>Making</u>: convert the sound into a print on a support in a spiraling groove;
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  - A head is placed on the groove;
  - It transmit the deviations of the groove to an electromagnetic transductor;



- <u>Making</u>: convert the sound into a print on a support in a spiraling groove;
- Playing:
  - A head is placed on the groove;
  - It transmit the deviations of the groove to an electromagnetic transductor;
  - An audio power amplifier allows un to actually hear the sound

#### Advantages:

- We capture the real sound
- Less mixing needed

Drawbacks:

- Worn out faster
- More fragile
- It is big

One device for one use: can we construct an "equivalent" of the physical computer, but for analogue model?  $\rightarrow$  is there a *general purpose* device?

## The GPAC

| Physical World        | Mathematical Model |  |
|-----------------------|--------------------|--|
| Laptop                | Turing machines    |  |
| Differential Analyzer | ?                  |  |

- Introduced by Claude Shannon in 1941;
- Mathematical model of the Differential Analizer;
- Model based on circuits, with several interconnected units doing basic operations





produit:  $e_0 = e_1 e_2$ 



additionneur:  $e_0 = -(e_1 + e_2)$ 



intégrateur:  $e_0 = e(0) - \int_0^t e_1(u) du$
## GPAC: how does it work?



$$\begin{cases} x'(t) = y(t) \\ y'(t) = -x(t) \\ x(0) = -1 \\ y(0) = 0 \end{cases} \Rightarrow \begin{cases} x(t) = \cos(t) \\ y(t) = -\sin(t) \\ y(t) = -\sin(t) \end{cases}$$

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Is GPAC a sufficiently powerful?

Is GPAC reasonable?

## Powerful: Other boxes



- Shannon: GPAC ≤ Turing Machines: A GPAC corresponds to (a projection of) a *polynomial* differential equation, which can be computed by a TM.
- Shannon: GPAC < Turing Machines: There exist computable functions, which are not projections of differential equations: e.g. Γ, ζ.

# We can actually program with polynomial ODE (Bournez, Graça, Pouly, Campagnolo, Hainry)

Transform this system of ODEs:

$$\begin{cases} y_1' = \sin^2 y_2 \\ y_2' = y_1 \cos y_2 - e^{e^{y_1} + t} \end{cases}$$

$$\begin{cases} y_1(0) = 0 \\ y_2(0) = 0 \end{cases}$$

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into a *polynomial* ODE:

$$\left\{\begin{array}{rcl} y_1' &=& y_3^2 \\ & & \end{array}\right.$$

$$y_1(0) = 0$$

considering  $y_3 = \sin y_2$ 

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into a *polynomial* ODE:

$$\left\{\begin{array}{rcl}
y_1' &=& y_3^2 \\
y_2' &=& y_1 y_4 - y_5 \\
\end{array}\right.$$

$$y_1(0) = 0$$
  
 $y_2(0) = 0$ 

considering  $y_3 = \sin y_2, y_4 = \cos y_2, y_5 = e^{e^{y_1} + t}$ 

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into a *polynomial* ODE:

$$\begin{cases} y_1' = y_3^2 \\ y_2' = y_1 y_4 - y_5 \\ y_3' = y_4 (y_1 y_4 - y_5) \end{cases}$$

$$y_1(0) = 0$$
  
 $y_2(0) = 0$   
 $y_3(0) = 0$ 

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into a *polynomial* ODE:

$$\begin{cases} y_1' = y_3^2 \\ y_2' = y_1y_4 - y_5 \\ y_3' = y_4(y_1y_4 - y_5) \\ y_4' = -y_3(y_1y_4 - y_5) \end{cases}$$

$$\begin{pmatrix}
y_1(0) &= 0 \\
y_2(0) &= 0 \\
y_3(0) &= 0 \\
y_4(0) &= 1
\end{pmatrix}$$

considering  $y_3 = \sin y_2, y_4 = \cos y_2$ ,  $y_5 = e^{e^{y_1} + t}$ 

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into a *polynomial* ODE:

$$\begin{cases} y_1' = y_3^2 \\ y_2' = y_1 y_4 - y_5 \\ y_3' = y_4 (y_1 y_4 - y_5) \\ y_4' = -y_3 (y_1 y_4 - y_5) \\ y_5' = y_5 (y_6 y_3^2 + 1) \end{cases} \begin{cases} y_1(0) = 0 \\ y_2(0) = 0 \\ y_3(0) = 0 \\ y_4(0) = 1 \\ y_5(0) = e \end{cases}$$

considering  $y_3 = \sin y_2, y_4 = \cos y_2, y_5 = e^{e^{y_1} + t}, y_6 = e^{y_1}$ 

Transform this system of ODEs:

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considering  $y_3 = \sin y_2, y_4 = \cos y_2, y_5 = e^{e^{y_1} + t}, y_6 = e^{y_1}$ 

### **Theorem** Every computable functions can be computed by polynomial ODE, and conversely



Turing Machines  $\leq$  GPAC

Is GPAC more powerful? 1

<sup>&</sup>lt;sup>1</sup>Fun fact: that's a part of my PhD subject 😂

## How much does it cost?



Fig. 5. A continuous system before and after an exponential speed-up.



Fig. 5. A continuous system before and after an exponential speed-up.

| $\theta$ solution of:              | $\phi$ solution of |
|------------------------------------|--------------------|
| y'=f(y)                            | z = z'             |
| with $f:\mathbb{R} \to \mathbb{R}$ | y' = f(y)z         |



Fig. 5. A continuous system before and after an exponential speed-up.

 $\begin{array}{ll} \theta \text{ solution of:} & \phi \text{ solution of:} \\ y' = f(y) & z = z' \\ \text{with } f : \mathbb{R} \to \mathbb{R} & y' = f(y)z \end{array}$ 

Re-scaling:  $\phi_1(t) = \theta(e^t)$ 



Fig. 5. A continuous system before and after an exponential speed-up.



With this definition of time, all computation can cost 1 time unit...



Fig. 5. A continuous system before and after an exponential speed-up.

Robust notion of time  $\rightarrow$  a quantity invariant by rescaling

The length remains the same

#### Time = Length of the curve

## Now space: Why it is not easy to solve ODEs

$$\mathbf{f}(0,\mathbf{x}) = \mathbf{g}(\mathbf{x})$$
 and  $\frac{\partial \mathbf{f}(t,\mathbf{x})}{\partial t} = \mathbf{u}(\mathbf{f}(t,\mathbf{x}),t,\mathbf{x}),$ 

• Non-computable in the general case, for **u** computable (Pour-El, Richards)

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- Non-computable in the general case, for **u** computable (Pour-El, Richards)
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- PSPACE-completeness on a bounded domain for **u** computable in polynomial-time (Kawamura, Ko)









- Computation at t = x at precision  $2^{-n}$ , with initial condition t = 0
- Computation at t = t<sub>0</sub> + <sup>x</sup>/<sub>2</sub> at precision 2<sup>-η(n)</sup>, with initial condition t<sub>0</sub> = 0 and t<sub>0</sub> = <sup>x</sup>/<sub>2</sub>
- Computation at  $t = t_0 + \frac{x}{4}$  at precision  $2^{-\gamma(n)}$ , with initial condition  $t_0 = 0$  and  $t_0 = \frac{x}{4}$  and  $t_0 = \frac{x}{2}$  and  $t_0 = \frac{3x}{4}$

#### Space = Precision of the computation

# Why computing with ODEs is interesting

- Differential analizers might use less energy
- Better representation of "real" systems: ODEs in mechanic, biology, chemistry...

## Your own cells do computation: treating signal, regulation of the metabolism

- Division
- Differentiation
- Migration

A major part of those are analogue computations with proteins

Once again, we live in an analogue world

## Biochemistry: Kohn's map of the mammalian cell cycle



Assuming at most binary reactions with mass action law kinetics:

## Theorem (Fages, Le Guludec, Bournez, Pouly)

- Any polynomial ODE can be encoded in a chemically feasible positive system of double dimension.
- I.e. The systems of elementary biochemical reactions on finite universes of molecules are Turing-complete in differential semantics.

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*Furthermore:* If the initial GPAC has a polynomial computational *complexity*, then the new system will also have a polynomial *complexity*.

• Can you compute faster with GPACs than with TMs?
$\bullet\,$  Can you compute faster with GPACs than with TMs? YES

- $\bullet\,$  Can you compute faster with GPACs than with TMs? YES
- Can you compute faster with Differential Analizer than with computers?

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- Are all ODEs representable by a GPAC? YES IF POLYNOMIAL
- Are all (poly) ODEs corresponding to a Differential Analizer? DON'T KNOW

## Conclusion

- We saw and define analogue models of computation
- We saw a mathematical description of those models
- We linked the notion of time and memory costs for TMs with that framework