Computability and complexity over the reals

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Introduction

We want to algebraically characterise PTIME and PSPACE...

Working on real numbers

- constant function 0,
- the projection functions π_i^p ,
- the function successor s,
- and that is closed under composition, minimisation and primitive recursion.

 $[O, \pi_i^p, \mathbf{s}; composition, primitive recursion, minimisation]$

Computability and complexity over the reals : how?

Example

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- What is a computable function over the reals?
- How do we define complexity over the reals?

The begining of algebraic characterisation: a class you know well

$$\frac{\delta f(\mathbf{x}, \mathbf{y})}{\delta \mathbf{x}} = f(\mathbf{x} + 1, \mathbf{y}) - f(\mathbf{x}, \mathbf{y})$$

Definition (Length ODE)

A function **f** is "length-ODE" definable (from u, g and h) if it is a solution of

$$f(0,\mathbf{y}) = \mathbf{g}(\mathbf{y})$$
 and $\frac{\delta \mathbf{f}(x,\mathbf{y})}{\delta \ell} = \mathbf{u}(\mathbf{f}(x,\mathbf{y}),\mathbf{h}(x,\mathbf{y}),x,\mathbf{y}).$ (1)

Formal synonym for right-hand side of (1): $\mathbf{f}(x+1,\mathbf{y}) = \mathbf{f}(x,\mathbf{y}) + (\ell(x+1) - \ell(x)) \cdot \mathbf{u}(\mathbf{f}(x,\mathbf{y}),\mathbf{h}(x,\mathbf{y}),x,\mathbf{y})$ Derivation with respect to the length = change of variable.

Variation when:

$$\ell(x+1) - \ell(x) \neq 0$$

Inspired by:

$$\frac{\delta f(x,\mathbf{y})}{\delta x} = \frac{\delta \ell(x)}{\delta x} \cdot \frac{\delta f(x,\mathbf{y})}{\delta \ell(x)}.$$

Motivation behind Length-ODEs



Fig. 5. A continuous system before and after an exponential speed-up.

heta solution of:	ϕ solution of:
y' = f(y)	z = z'
$f:\mathbb{R} \to \mathbb{R}$	y' = f(y)z

Motivation behind Length-ODEs



Fig. 5. A continuous system before and after an exponential speed-up.

Re-scaling: $\phi_1(t) = \theta(e^t)$

Now "time-complexity" is measured by the length of the solution curve of the ODE.

Invariance by rescaling

$$f(0) = 2$$

$$\frac{\delta f}{\delta \ell}(x) = f(x) \cdot f(x) - f(x)$$

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Unique solution : $f(x) = 2^{2^{\ell(x)}}$

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• We have
$$f(x) = F(z)$$

•
$$F(z+1) = 2^{2^z+2^z} = F(z)F(z)$$

• Then, F(z+1) = F(z) + (z+1-z)(F(z)F(z) - F(z))

We consider

$$\mathbb{LDL} = [0, 1, \pi_i^k, \ell(x), +, -, \times, cond(x);$$

composition, linear length ODE]

Theorem (Bournez & Durand, '19) $\mathbb{LDL}\cap\mathbb{N}^{\mathbb{N}}=\mathsf{PTIME}\cap\mathbb{N}^{\mathbb{N}}$

First step: real sequences

Definition $f : \mathbb{R} \to \mathbb{R}$ is an effective limit of $\overline{f} : \mathbb{R} \times \mathbb{N} \to \mathbb{R}$ if $|f(x) - \overline{f}(x, 2^n)| \le 2^{-n}$

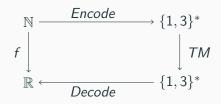
<u>Key observation</u> : \overline{f} computable in polynomial time \Rightarrow f computable in polynomial time.

We consider:

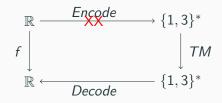
$$\overline{\mathbb{LDL}^{\bullet}} = [\mathbf{0}, \mathbf{1}, \pi_i^k, \ell(x), +, -, \times, \overline{\mathrm{cond}}(x), \frac{x}{2};$$

composition, linear length ODE, effective limit]

Theorem (B., Bournez, MCU22) $FPTIME \cap \mathbb{R}^{\mathbb{N}} = \overline{\mathbb{LDL}^{\bullet}} \cap \mathbb{R}^{\mathbb{N}}$



Second step: functions over the reals with discrete ODEs



We consider:

$$\overline{\mathbb{LDL}^{\circ}} = [\mathbf{0}, \mathbf{1}, \pi_i^k, \ell(x), +, -, \tanh, \frac{x}{2}, \frac{x}{3};$$

composition, linear length ODE, effective limit]

Theorem (B., Bournez, MFCS23)

 $\overline{\mathbb{L}\mathbb{D}\mathbb{L}^{\circ}}\cap\mathbb{R}^{\mathbb{R}}\ =\mathsf{FPTIME}\cap\mathbb{R}^{\mathbb{R}}$

Definition (Robust linear ODE)

A bounded function **f** is a robustly linear ODE definable (with **u** essentially linear in $\mathbf{f}(x, \mathbf{y})$, **g** and **h**) if:

1. it is a solution of

 $\mathbf{f}(0,\mathbf{y}) = \mathbf{g}(\mathbf{y})$ and $\frac{\delta \mathbf{f}(x,\mathbf{y})}{\delta x} = \mathbf{u}(\mathbf{f}(x,\mathbf{y}),\mathbf{h}(x,\mathbf{y}),x,\mathbf{y}),$

2. the ODE is (polynomially) numerically stable.

We consider:

$$\overline{\mathbb{RLD}^{\circ}} = [\mathbf{0}, \mathbf{1}, \pi_i^k, \ell(x), +, -, \tanh, \frac{x}{2}, \frac{x}{3};$$

composition, robust linear ODE, effective limit]

Theorem (B., Bournez, MFCS23) $\overline{\mathbb{RLD}^{\circ}} \cap \mathbb{R}^{\mathbb{R}} = FPSPACE \cap \mathbb{R}^{\mathbb{R}}$

Third step: Functions over the reals with continuous ODEs

A function $f:\mathbb{R}\to\mathbb{R}$ is robustly ODE definable (from initial condition g, and dynamic u) if

• it corresponds to the solution of the following continuous ODE:

$$\mathbf{f}(0,\mathbf{x}) = \mathbf{g}(\mathbf{x})$$
 and $\frac{\partial \mathbf{f}(t,\mathbf{x})}{\partial t} = \mathbf{u}(\mathbf{f}(t,\mathbf{x}),\mathbf{h}(t,\mathbf{x}),t,\mathbf{x}),$ (2)

 ∃Δ ∈ Q^{*}₊, and some polynomial p such that the previous ODE is (polynomially) numerically stable on [0, Δ].

i.e. for all integer *n*, considering $\eta(n) = p(n + \ell(\mathbf{x}))$ we can compute $\mathbf{f}(t, \mathbf{x})$ at 2^{-n} by working a precision $2^{-\eta(n)}$.

For t ≥ Δ, we can compute f(t, x) by computing some approximation f(t/2, x) of f(t/2, x) at precision ε(n).

i.e. of $\Phi(\mathbf{g}(x), t/2)$, and then some approximation of $\Phi(\mathbf{f}(t/2, \mathbf{y}), t/2)$ at 2^{-n} , working at precision $2^{-\eta(n)}$.

We consider :

$$\overline{\mathbb{RCD}} = [0, 1, \pi_i^k, +, -, \times, \tanh, \cos, \pi, \frac{x}{2}, \frac{x}{3};$$

Theorem (B., Bournez, ICALP24 Track B) $\overline{\mathbb{RCD}} \cap \mathbb{R}^{\mathbb{R}} = FPSPACE \cap \mathbb{R}^{\mathbb{R}}$

Conclusion

- We now have "natural" algebraic characterisations for functions over the reals computable in FPTIME and FPSPACE.
- Further works:
 - Cover other complexity classes
 - See what we can say for more general functions