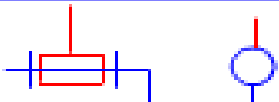
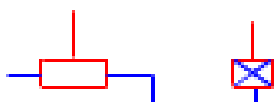
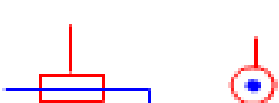
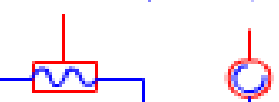
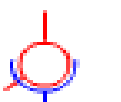

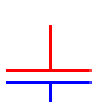
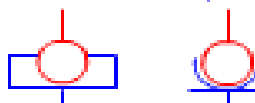
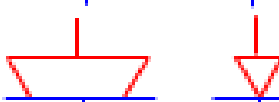
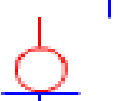
	NOM : ..... Classe : .....	Activités
	Prénom : ..... Date : .....	<input type="checkbox"/> Etude de dossier technique <input checked="" type="checkbox"/> Activité pratique <input type="checkbox"/> Travaux dirigés <input type="checkbox"/> Cours
<b>Modélisation mécanique : Les liaisons</b>		

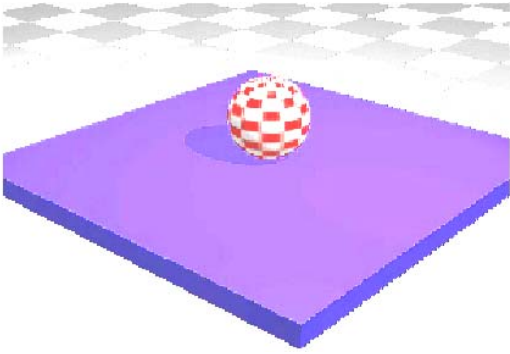
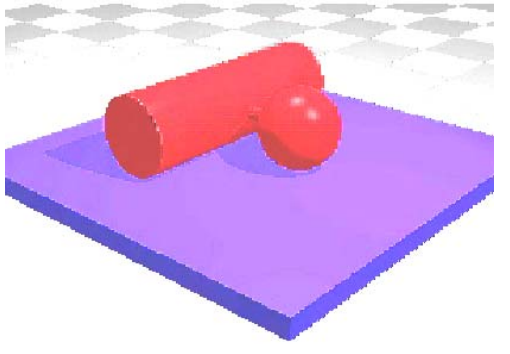
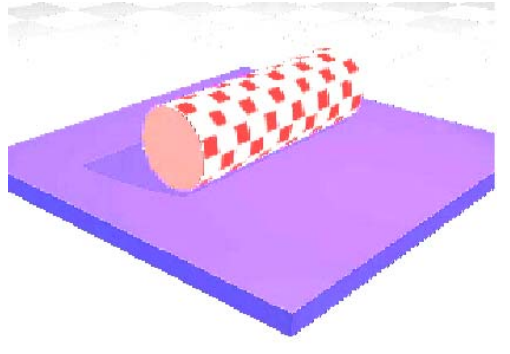
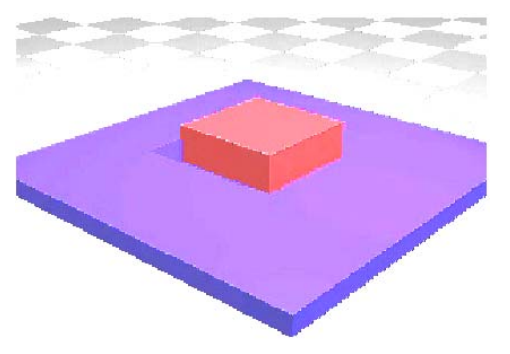
Sur un poste informatique, allez sur le site « NewEcligne ». (<https://sites.google.com/view/newecligne/>)  
 Allez dans « Mécanique », puis « Modélisation » => « Les liaisons ».


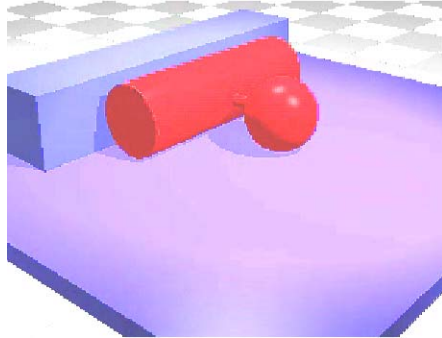
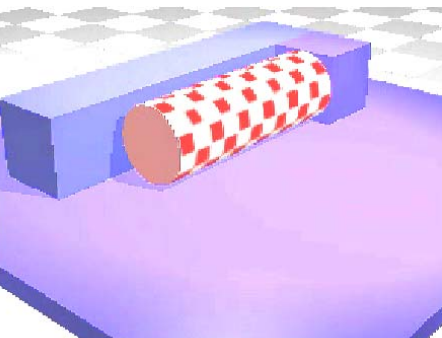
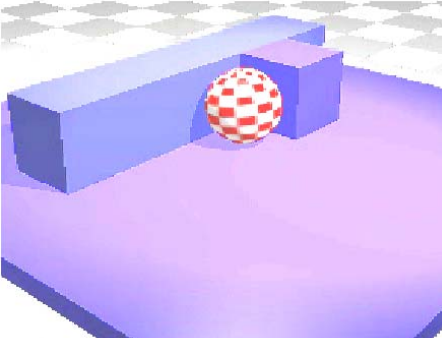
1/ **Visionnez** le chapitre « Cours », puis **complétez** le tableau: repassez en couleur les schémas et complétez le nom de la liaison

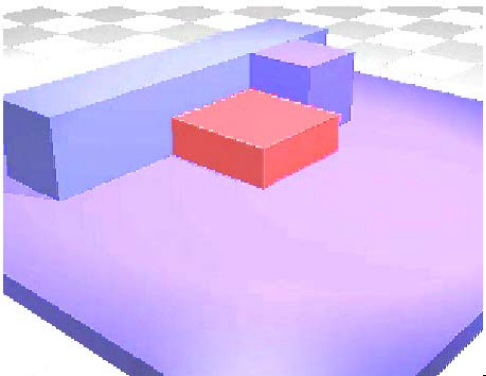
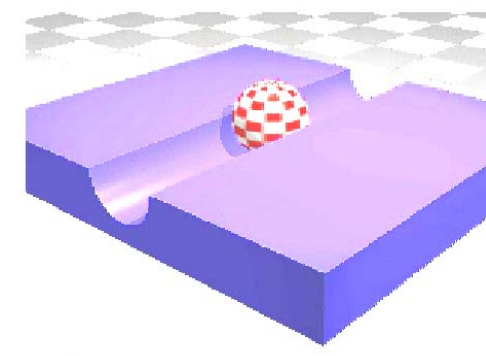
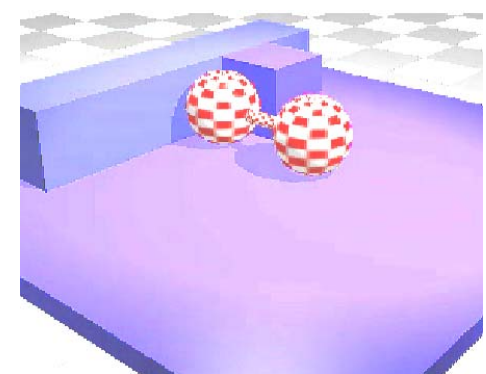
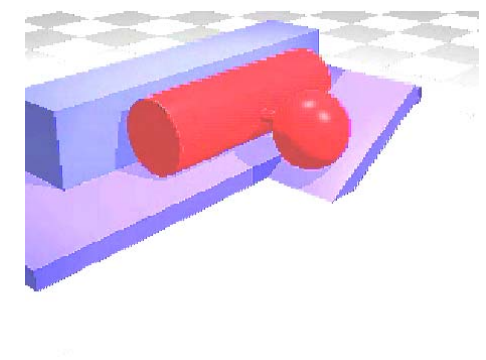
T	R	Nom de la liaison	Schéma
0	1		
1	0		
1	1		
1	1		
0	2		
0	3		
2	1		
1	3		
2	2		
2	3		

2/ Revenez dans Modélisation/Les liaisons puis traitez les exercices tout en **complétant** le document suivant :

Colonne « degrés de liberté » : mettez 1 si le mouvement est possible sans changer la nature du contact, 0 si il change la nature du contact.

Contact	Degrés de liberté	Nom de la liaison								
	<table border="1"> <tr> <td></td> <td>T</td> <td>R</td> </tr> <tr> <td>X</td> <td colspan="2" rowspan="3"> </td> </tr> <tr> <td>Y</td> </tr> <tr> <td>Z</td> </tr> </table>		T	R	X			Y	Z	
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Contact	Degrés de liberté	Nom de la liaison												
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