# MA 101: Key Concepts and Results

Vijaysekhar Chellaboina

Professor Mahindra École Centrale

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🐥 MA101 🍐 Summary 🐥

### Real Numbers $\mathbb{R}$

#### Basics

- Operations:  $+, \times, -, \div$ , identities: 0, 1
- Relational:  $<, \leq, >, \geq$
- Concepts: bounded, max, sup, inf, min, absolute value
- ▶ Subsets: Integers  $\mathbb{N}$ , rationals  $\mathbb{Q}$ , and irrationals  $\mathbb{R} \setminus \mathbb{Q}$

- Every two numbers will satisfy either x < y, y < x, or x = y
- Every upper bounded set has a supremum
- Rationals are dense in  $\mathbb{R}$ ; so are irrationals
- $x^2 = 2$  has solutions in  $\mathbb{R} \setminus \mathbb{Q}$ ; No solution in  $\mathbb{R}$  for  $x^2 + 1 = 0$

## Complex Numbers $\mathbb C$

#### Basics

- Starts with *i*, the solution to  $x^2 + 1 = 0$
- Operations:  $+, \times, -, \div$ ; identities: 0, 1
- No relational operators
- Concepts: Modulus/absolute value, argument/phase
- Subsets: Real numbers  $\mathbb{R}$ , Imaginary numbers

- $z = |z|e^{i\theta}$  where  $\theta = \arg(z)$  (what is  $\arg(z)$ ?)
- Euler's identity:  $e^{i\theta} = \cos(\theta) + i\sin(\theta)$

• If 
$$z^n = 1$$
 then  $z^n = e^{i2k\pi}$ ,  $k \in \mathbb{N}$ . Hence,  $z = e^{i\frac{2k\pi}{n}}$ ,  $k \in \mathbb{N}$ 

# Sequences

#### Basics

- A sequence is a function  $f : \mathbb{N} \to \mathbb{R}$  or  $\mathbb{C}$
- Concepts: Limit, convergence, divergence
- ▶  $\lim_{n\to\infty} a_n = L$ : For every  $\varepsilon > 0$ ,  $\exists N$  s.t.  $|a_n L| < \varepsilon$ ,  $n \ge N$
- ▶  $a_n \to \infty$ : For every M > 0,  $\exists N$  s.t.  $a_n > M$ ,  $n \ge N$ .

- A convergent sequence is bounded; Converse, not true:  $(-1)^n$
- An alternating sequence is divergent:  $(-1)^n$ ,  $i^n$ , sin(n)
- A monotonic sequence is convergent iff it is bounded
- Don't forget the squeeze theorem!

### Series

#### Basics

- A series is a sequence  $\sum_{k=1}^{n} a_n$
- Concepts: Limit, convergence, divergence

- ▶ If a nonnegative series converges then  $a_n \rightarrow 0$  as  $n \rightarrow \infty$
- Converse is not always true:  $\sum_{k=1}^{n} \frac{1}{n}$

• But 
$$\sum_{k=1}^{n} \frac{1}{n^p}$$
 converges for all  $p > 1$ 

- Ratio, root tests can be quite handy!
- Don't forget the comparison test!

# Remarks on Sequences and Series

# **Continuous Functions**

#### Basics

- ► f is continuous at x if  $\lim_{h\to 0} f(x+h) = f(x)$
- Same as:  $\lim_{h \to 0^+} f(x+h) = \lim_{h \to 0^-} f(x+h) = f(x)$
- Polynomials, trigonometrics, exponential, logarithmics

- Sums, products, composites of continuous functions are continuous on domain of intersection
- Bolzano's theorem: if f(a)f(b) < 0 then f(c) = 0 for some c ∈ (a, b)</p>
- Extreme value theorem: continuous functions on closed intervals have maximum and minimum

## **Convex Functions**

#### Basics

- ▶ Let *I* be an interval (closed, open, or semi-open)
- $f: \mathcal{I} \to \mathbb{R}$  is convex if for all  $x, y \in \mathcal{I}$  and  $\lambda \in (0, 1)$ ,

$$f(\lambda x + (1-\lambda)y) \leq \lambda f(x) + (1-\lambda)f(y)$$

• Examples:  $f(x) = x^2$  on  $\mathbb{R}$ ,  $-\ln(x)$  on  $[0,\infty)$ 

- If f has a local minimum at x then it is a global minimum
- A convex f is continuous on the interior of  $\mathcal{I}$
- If  $f''(x) \ge 0 \ \forall x \in \mathcal{I}$  then f is convex

# Differentiable Functions I

- f is differentiable at x if  $\lim_{h\to 0} \frac{f(x+h)-f(x)}{h}$  exists
- Denoted by f', it is the derivative of f
- If f' exists at x then f is continuous at x
- Chain rule 1: (fg)' = f'g + fg'
- Chain rule 2:  $(f \circ g)' = (f' \circ g) \cdot g'$
- Local minimum: if f has a local minimum at x then f'(x) = 0 and f''(x) ≥ 0
- Partial converse: if at x, f'(x) = 0 and f''(x) > 0 then f has a local minimum at x

### Differentiable Functions II

#### Key Results

- ▶ Rolle's thm: If f(a) = f(b) then f'(c) = 0 for some  $c \in (a, b)$
- Mean value theorem:  $\exists c \in (a, b)$  such that

$$f^{'}(c)=rac{f(b)-f(a)}{b-a}$$

▶ Taylor series formula: there exists  $c \in (x, x + h)$  such that

$$f(x+h) = f(x) + hf'(x) + \frac{h^2}{2!}f''(x) + \dots + \frac{h^{n+1}}{(n+1)!}f^{(n+1)}(c)$$

• Anti-derivative: If g = f' then g is the anti-derivative of f

## Integrals I

- Area under a curve; area of shapes other than polygons
- Partitions, Riemann sums, integrability
- Bounded functions are integrable on finite intervals
- Infinite interval case is a bit more tricky
- Since continuous functions on finite intervals are bounded they are integrable

FTC I: If 
$$F(x) = \int_{a}^{x} f(t) dt$$
 then  $F'(x) = f(x)$ 

FTC II: If G is anti-derivative of g then

$$\int_{a}^{b} g(t) \mathrm{d}t = G(b) - G(a)$$

# Integrals II

Lebinitz formula:

$$\frac{\mathrm{d}}{\mathrm{d}x}\int_{a}^{g(x)}f(t)\mathrm{d}t=f(g(x))g'(x)$$

Change of variables:

$$\int_{g(a)}^{g(b)} f(t) \mathrm{d}t = \int_{a}^{b} f(g(u))g'(u) \mathrm{d}u$$

Integration by parts:

$$\int f(t)g'(t)dt = f(t)g(t) - \int f'(t)g(t)dt + C$$

### Differential Equations I

- Consider the 1st order ODE: y' + P(x)y = Q(x)
- Solutions exists and unique if P and Q are continuous on  $\mathcal{I}$
- ► Homogeneous solution:  $y(x) = y(a)e^{-A(x)}$  where  $a \in \mathcal{I}$  and  $A(x) = \int_{a}^{x} P(t) dt$
- Nonhomogeneous solution:

$$y(x) = y(a)e^{-A(x)} + e^{-A(x)} \int_{a}^{x} Q(t)e^{A(t)} dt$$

### Differential Equations II

- Consider the 2nd order ODE: y'' + ay' + by = R(x)
- Characteristic equation:  $r^2 + ar + b = 0$  with roots  $r_1$ ,  $r_2$
- Complementary (homogeneous) solution:
  - $y(x) = C_1 e^{r_1 x} + C_2 e^{r_2 x}$  if  $r_1 \neq r_2$  and real
  - $y(x) = C_1 e^{\alpha x} \cos(\beta x) + C_2 e^{\alpha x} \sin(\beta x)$  if  $r_{1,2} = \alpha \pm i\beta$
  - $y(x) = C_1 e^{rx} + C_2 x e^{rx}$  if  $r_1 = r_2 = r$
- Nonhomogeneous solution:
  - methods of undetermined coefficients (good for polynomials/exponetials)
  - variation of parameters (general but tedious)

### Vector Calculus

- Let  $\overline{r}(t) = (x(t), y(t))$  denote a curve
- Length of a curve:

$$\int_{a}^{b} \|\bar{r}'(t)\| \mathrm{d}t$$

- Of course,  $\|\overline{r}'(t)\| = \sqrt{x'^2(t) + {y'}^2(t)}$
- Let r
  (t), v
  (t), and a
  (t) denote position, velocity, and acceleration, respectively
- The curvature

$$\kappa(t) = rac{\|ar{a}(t) imes ar{v}(t)\|}{\|ar{v}(t)\|^3}$$